



Electromagnetics:  
Electromagnetic Field Theory

## Skin Depth & Power Flow

1

### Lecture Outline

- Skin Depth  $\delta$
- Power Flow

2

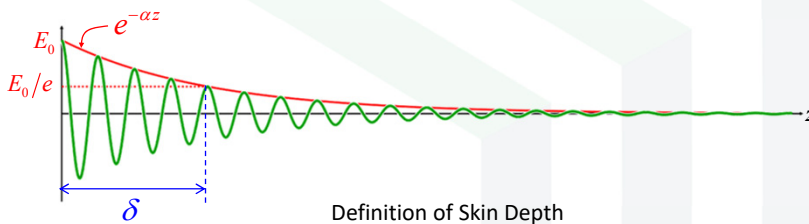
# Skin Depth $\delta$

Slide 3

3

## Skin Depth $\delta$

Waves in good conductors attenuate very quickly. The distance over which they decay by a factor of  $1/e$  is called the skin depth  $\delta$ .



Definition of Skin Depth

$$\delta = 1/\alpha \text{ (m)}$$

Relation to Impedance

$$\eta = \frac{1+j}{\sigma\delta} = \frac{\sqrt{2}}{\sigma\delta} \angle 45^\circ$$

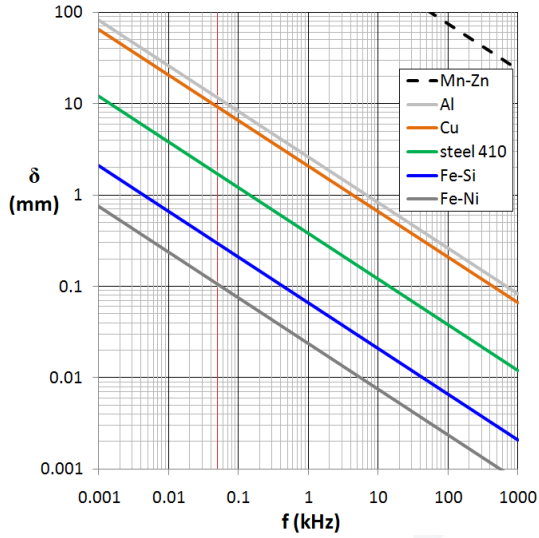
In Terms of Fundamental Parameters

$$\delta = \sqrt{\frac{2}{\omega\mu\sigma}} = \frac{1}{\sqrt{\pi f \mu\sigma}}$$

Slide 4

4

# Skin Depth for Various Materials

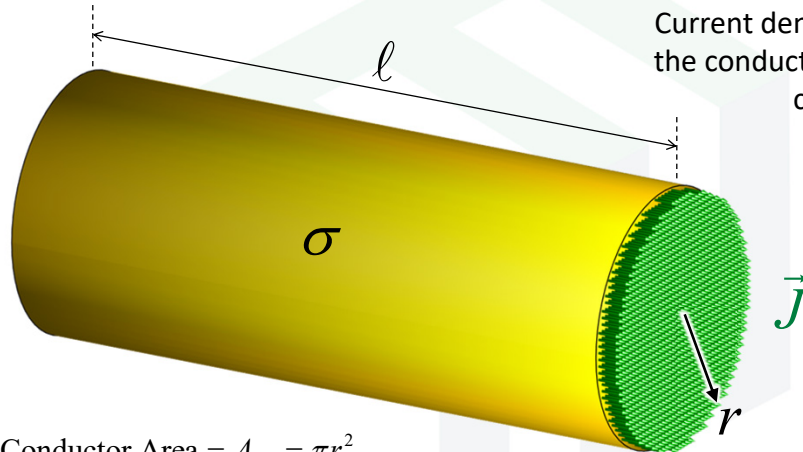


Skin depth vs. frequency for some materials at room temperature, red vertical line denotes 50 Hz frequency:  
 Mn-Zn – magnetically soft ferrite  
 Al – metallic aluminum  
 Cu – metallic copper  
 steel 410 – magnetic stainless steel  
 Fe-Si – grain-oriented electrical steel  
 Fe-Ni – high-permeability permalloy (80%Ni-20%Fe)

[https://en.wikipedia.org/wiki/Skin\\_effect](https://en.wikipedia.org/wiki/Skin_effect)

5

## DC Resistance, $R_{DC}$



Current density is uniform throughout the conductor so the entire conductor contributes to current flow.

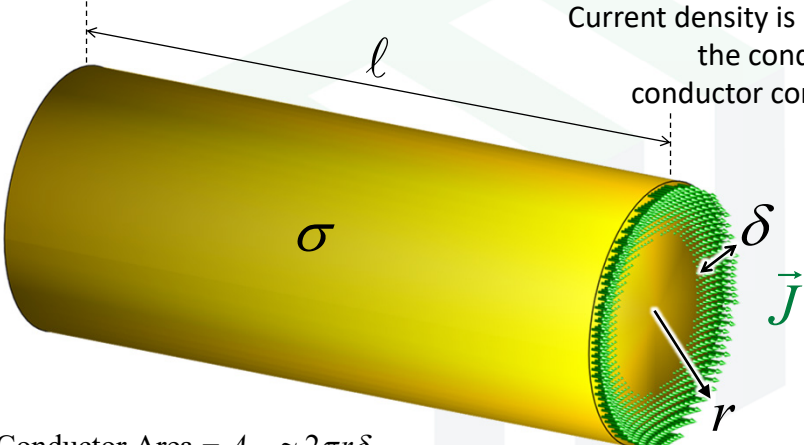
$$\text{Conductor Area} = A_{DC} = \pi r^2$$

$$R_{DC} = \frac{l}{\sigma A_{DC}} = \frac{l}{\sigma \pi r^2}$$

6


## AC Resistance, $R_{AC}$

Current density is NOT uniform throughout the conductor so only part of the conductor contributes to current flow.



Conductor Area =  $A_{AC} \approx 2\pi r\delta$

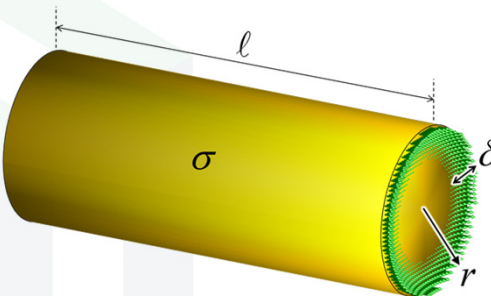
$$R_{AC} = \frac{l}{\sigma A_{AC}} = \frac{l}{2\pi r\sigma\delta} \quad \text{for } \delta \ll r$$

 Slide 7

7


## Conductor Area for AC Resistance

Area Described by  $\delta$

$$\begin{aligned} A_{AC} &= \pi r^2 - \pi(r - \delta)^2 \\ &= \pi r^2 - \pi(r^2 - 2r\delta + \delta^2) \\ &= \pi r^2 - \pi r^2 + 2\pi r\delta - \pi\delta^2 \\ &= 2\pi r\delta - \pi\delta^2 \quad \text{for } \delta \ll r \\ &\approx 2\pi r\delta \end{aligned}$$


Effective Conductor Area

$$A_{AC} \approx 2\pi r\delta \quad \text{for } \delta \ll r$$

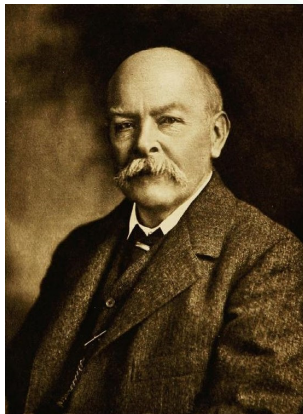
 Slide 8

8

# Notes on Skin Depth and AC Resistance

- High frequencies experience so much loss that they do not penetrate very far into a conductor.
- The depth of penetration is called skin depth  $\delta$ .
- Due to the skin depth at high frequencies, only part of the conductor contributes to current flow. This makes resistance increase as a function of frequency.
- Drawbacks
  - High frequencies experience more loss.
  - Signals get distorted
- Benefits
  - Conductors can be made hollow – cheaper, lighter, etc.
  - Can make inner part of conductor out of a different material.

# Power Flow



John Henry Poynting

1852 – 1914

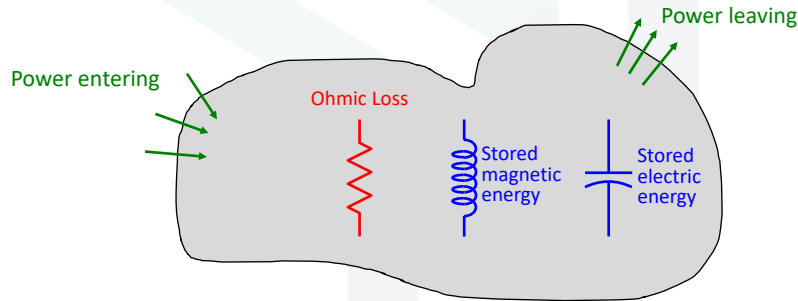
Academic Advisor: James Clerk Maxwell

[https://en.wikipedia.org/wiki/John\\_Henry\\_Poynting](https://en.wikipedia.org/wiki/John_Henry_Poynting)

# Poynting's Theorem

Poynting's theorem is a conservation of power equation.

The total power leaving a volume must be equal to the rate of decrease of the total energy stored in the field plus the energy lost due to heat (or something else).



$$\underbrace{\oint_S (\vec{E} \times \vec{H}) \cdot d\vec{s}}_{\text{Total power leaving volume}} = - \underbrace{\frac{1}{2} \frac{\partial}{\partial t} \iiint_V (\mu |\vec{H}|^2 + \epsilon |\vec{E}|^2) dv}_{\text{Rate of decrease of stored electric and magnetic energy}} - \underbrace{\iiint_V (\sigma |\vec{E}|^2) dv}_{\text{Ohmic power dissipated}}$$

# Poynting Vector

From Poynting's theorem, the term responsible for power leaving the volume is identified.

$$\oint_S (\vec{E} \times \vec{H}) \cdot d\vec{s} = - \frac{1}{2} \frac{\partial}{\partial t} \iiint_V (\mu |\vec{H}|^2 + \epsilon |\vec{E}|^2) dv - \iiint_V (\sigma |\vec{E}|^2) dv$$

Here flux is being integrated to get total power. The argument must be power density (W/m<sup>2</sup>). This term is called the *instantaneous Poynting vector*.

$$\vec{\phi}(t) = \vec{E}(t) \times \vec{H}(t)$$

Due to the cross product, the Poynting vector  $\vec{\phi}$  is perpendicular to both  $\vec{E}$  and  $\vec{H}$ . For LHI materials, the Poynting vector is in the same direction as the wave vector.

$$\vec{E} \perp \vec{k} \perp \vec{H} \qquad \vec{E} \perp \vec{\phi} \perp \vec{H} \qquad \vec{\phi} \parallel \vec{k}$$

## Instantaneous Poynting Vector $\vec{\rho}(t)$

Recall the electric and magnetic field components of a plane wave travelling in the  $+z$  direction can be written in the time-domain as

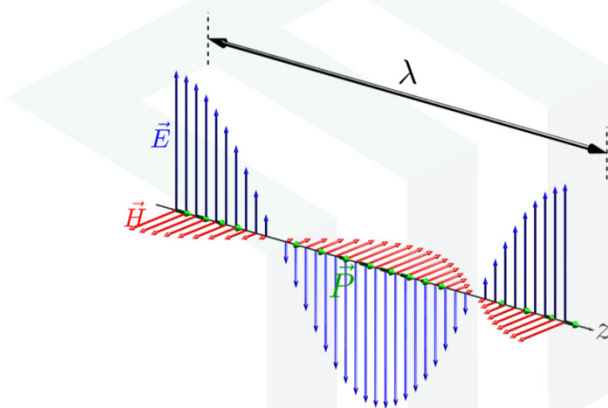
$$\vec{E}(z,t) = E_0 e^{-\alpha z} \cos(\omega t - \beta z) \hat{a}_x \quad \vec{H}(z,t) = \frac{E_0}{|\eta|} e^{-\alpha z} \cos(\omega t - \beta z - \angle \eta) \hat{a}_y$$

Substituting these expressions into the definition of the instantaneous Poynting vector gives

$$\begin{aligned} \vec{\rho}(t) &= \vec{E}(t) \times \vec{H}(t) \\ &= \left[ E_0 e^{-\alpha z} \cos(\omega t - \beta z) \hat{a}_x \right] \times \left[ \frac{E_0}{|\eta|} e^{-\alpha z} \cos(\omega t - \beta z - \angle \eta) \hat{a}_y \right] \\ \vec{\rho}(t) &= \underbrace{\frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle \eta) \hat{a}_z}_{\text{Constant power flow}} + \underbrace{\frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(2\omega t - 2\beta z - \angle \eta) \hat{a}_z}_{\text{Rapidly oscillating fluctuation in power flow}} \end{aligned}$$

13

## Animation of Instantaneous Power Flow



$$\vec{\rho}(t) = \underbrace{\frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle \eta) \hat{a}_z}_{\text{Constant power flow}} + \underbrace{\frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(2\omega t - 2\beta z - \angle \eta) \hat{a}_z}_{\text{Rapidly oscillating fluctuation in power flow}}$$

14

## Average Poynting Vector $\vec{\phi}_{\text{avg}}$

The instantaneous power flow is rarely of interest because the rapidly fluctuating term does not transport any net power. The more practical and useful quantity is the time-average Poynting Vector  $\vec{\phi}_{\text{avg}}$ .

To obtain the time-average Poynting vector  $\vec{\phi}_{\text{avg}}$ , integrate over one wave cycle  $\tau$ .

$$\vec{\phi}_{\text{avg}} = \frac{1}{\tau} \int_0^{\tau} \vec{\phi}(t) dt$$

$$= \frac{1}{\tau} \int_0^{\tau} \left[ \frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle\eta) \hat{a}_z \right] dt + \frac{1}{\tau} \int_0^{\tau} \left[ \frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(2\omega t - 2\beta z - \angle\eta) \hat{a}_z \right] dt$$

Integrating cosine over one wave cycle equals zero because cosine is both negative and positive equally.

$$\vec{\phi}_{\text{avg}} = \frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle\eta) \hat{a}_z$$

## Complex Poynting Vector $\vec{\phi}$

For time-harmonic signals, the frequency-domain Poynting vector is complex.

$$\vec{\phi} = \vec{E} \times \vec{H}^*$$

The field expressions for the plane wave are

$$\vec{E}(z) = E_0 e^{-\gamma z} \hat{a}_x \quad \vec{H}(z) = \frac{E_0}{|\eta|} e^{-\gamma z} e^{-j\angle\eta} \hat{a}_y$$

Substituting these into the definition of complex Poynting vector gives

$$\begin{aligned} \vec{\phi} &= \left[ E_0 e^{-\gamma z} \hat{a}_x \right] \times \left[ \frac{E_0}{|\eta|} e^{-\gamma z} e^{-j\angle\eta} \hat{a}_y \right]^* \\ &= \left[ E_0 e^{-\alpha z} e^{-j\beta z} \hat{a}_x \right] \times \left[ \frac{E_0^*}{|\eta|} e^{-\alpha z} e^{j\beta z} e^{j\angle\eta} \hat{a}_y \right] \\ &= \frac{|E_0|^2}{|\eta|} e^{-2\alpha z} e^{j\angle\eta} (\hat{a}_x \times \hat{a}_y) \end{aligned} \quad \rightarrow \quad \vec{\phi} = \frac{E_0^2}{|\eta|} e^{-2\alpha z} e^{j\angle\eta} \hat{a}_z$$



## RMS Poynting Vector $\vec{\phi}_{\text{avg}}$

The complex Poynting vector  $\vec{\phi}$  is like the instantaneous Poynting vector  $\vec{\phi}(t)$  and contains the rapidly varying fluctuations in power flow.

A more meaningful quantity is the root-mean-square (RMS) power flow that is easily calculated from the complex Poynting vector.

$$\vec{\phi}_{\text{avg}} = \frac{1}{2} \text{Re}[\vec{\phi}] = \frac{1}{2} \text{Re}[\vec{E} \times \vec{H}^*]$$

$$\begin{aligned} \vec{\phi}_{\text{avg}} &= \frac{1}{2} \text{Re}[\vec{\phi}] \\ &= \frac{1}{2} \text{Re} \left[ \frac{E_0^2}{|\eta|} e^{-2\alpha z} e^{j\angle\eta} \hat{a}_z \right] \\ &= \frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle\eta) \hat{a}_z \end{aligned}$$

$$\vec{\phi}_{\text{avg}} = \frac{E_0^2}{2|\eta|} e^{-2\alpha z} \cos(\angle\eta) \hat{a}_z$$

## Total Power

The Poynting vector is a power density with units of W/m<sup>2</sup>.

To calculate total power flow through some area, integrate the Poynting vector over that area.

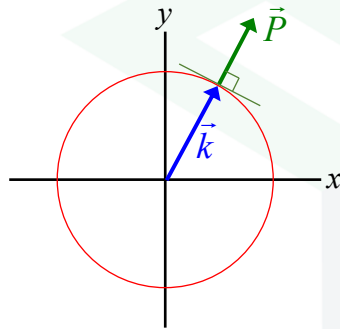
$$P(t) = \iint_S \vec{\phi}(t) \cdot d\vec{s}$$

The average power flow is simply calculated from the average Poynting vector.

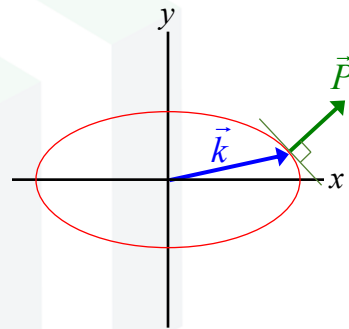
$$P_{\text{avg}} = \iint_S \vec{\phi}_{\text{avg}} \cdot d\vec{s}$$

# Index Ellipsoids and Power Flow

## Isotropic Materials



## Anisotropic Materials



Phase propagates in the direction of  $\vec{k}$ . Therefore, the refractive index  $n$  derived from  $|\vec{k}|$  is best described as the phase refractive index  $n_p$ . Velocity here is the phase velocity  $\vec{v}_p$ .

Power propagates in the direction of the Poynting vector  $\vec{\rho}$  which is always normal to the surface of the index ellipsoid. From this, we can define a group refractive index  $n_g$  and group velocity  $\vec{v}_g$ .