



Electromagnetics:
Electromagnetic Field Theory
Statics & Dynamics

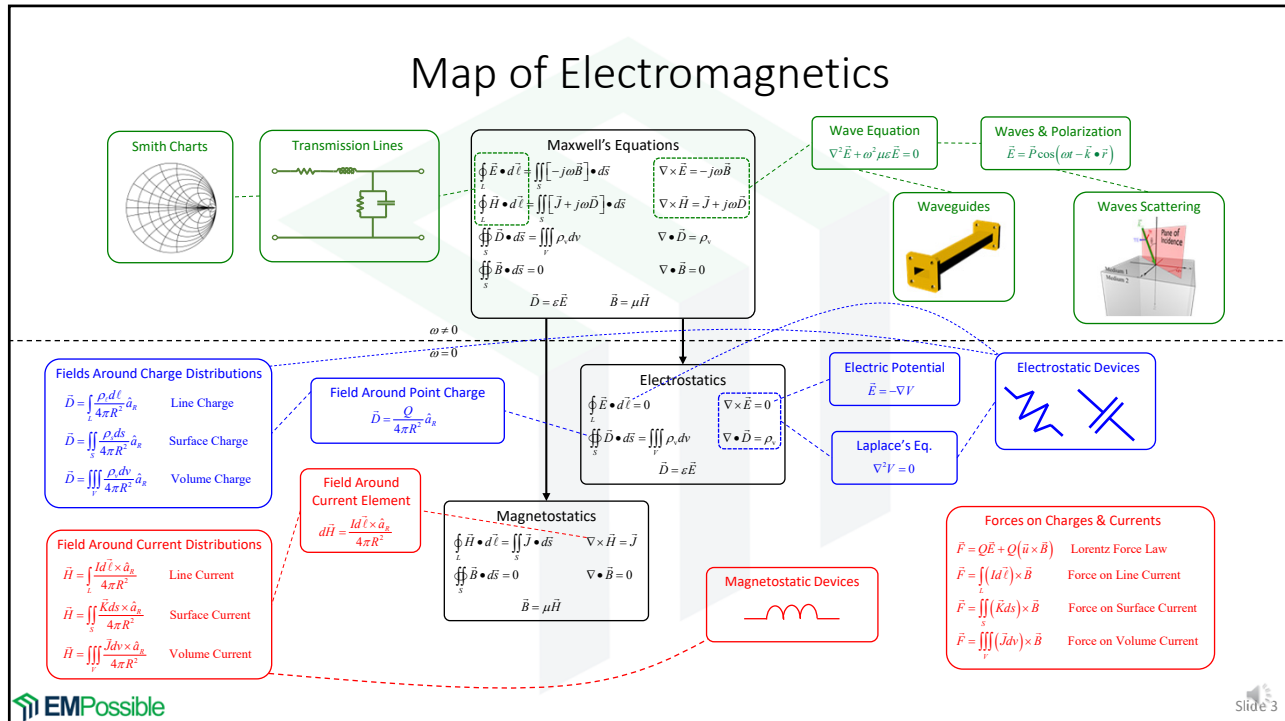


1

Outline

- Map of Electromagnetics 101
- Conditions to apply static approximation
- Consequences of static approximation

2



3

Conditions to Apply Static Approximation

4

Conditions for Statics

Situation #1 – At $\omega = 0$

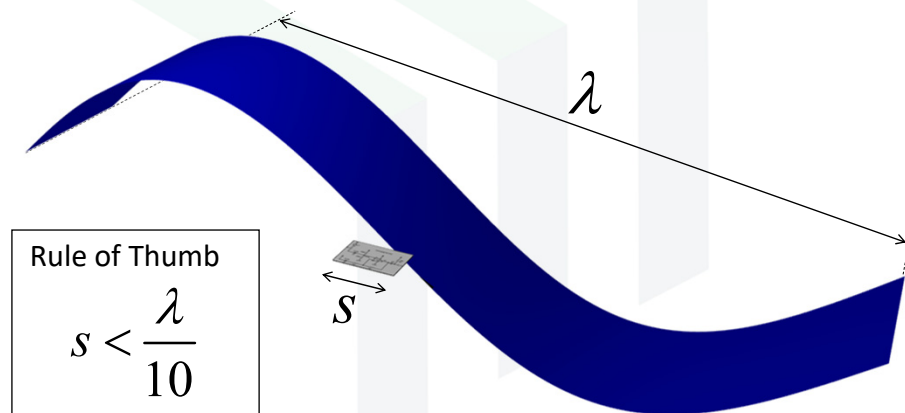
At DC (i.e. $\omega = 0$), nothing changes with time.

$$\omega \rightarrow 0$$

$$\frac{\partial}{\partial t} \rightarrow 0$$

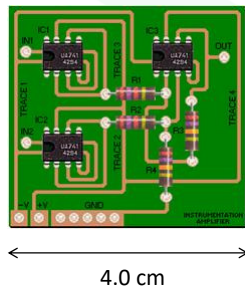
Conditions for Statics

Situation #2 – When size s of a problem is much less than the wavelength λ .



Example #1

Estimate the maximum frequency that this circuit can be analyzed using standard circuit theory?



Note: This does not mean that circuits cannot be designed at higher frequencies. It is just that these designs cannot use ordinary circuit theory.

Solution

The maximum dimension s of the circuit was given to be

$$s = 4.0 \text{ cm}$$

The minimum wavelength λ_{\min} is

$$\lambda_{\min} \approx 10s = 10(4.0 \text{ cm}) = 40 \text{ cm}$$

It follows that the maximum frequency f_{\max} is

$$f_{\max} = \frac{c_0}{\lambda_{\min}} = \frac{3.0 \times 10^8 \text{ m/s}}{0.40 \text{ m}} = \boxed{750 \text{ MHz}}$$

Consequences of Static Approximation

Maxwell's Equations for Static Fields

	Integral Form	Differential Form
Time-Domain	$\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_v dv$ <p style="text-align: center;">Most general form</p> $\oiint_S \vec{B} \cdot d\vec{s} = 0$ $\oint_L \vec{E} \cdot d\vec{\ell} = -\iint_S \left[\frac{\partial \vec{P}}{\partial t} \right] \cdot d\vec{s}$ $\oint_L \vec{H} \cdot d\vec{\ell} = \iint_S \left[\vec{J} + \frac{\partial \vec{D}}{\partial t} \right] \cdot d\vec{s}$	$\nabla \cdot \vec{D} = \rho_v$ $\nabla \cdot \vec{B} = 0$ $\nabla \times \vec{E} = -\frac{\partial \vec{P}}{\partial t}$ $\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$
Frequency-Domain	$\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_v dv$ $\oiint_S \vec{B} \cdot d\vec{s} = 0$ $\oint_L \vec{E} \cdot d\vec{\ell} = -\iint_S \left[j \vec{P} \right] \cdot d\vec{s}$ $\oint_L \vec{H} \cdot d\vec{\ell} = \iint_S \left[\vec{J} + j\omega \vec{D} \right] \cdot d\vec{s}$	$\nabla \cdot \vec{D} = \rho_v$ $\nabla \cdot \vec{B} = 0$ <p style="text-align: center;">Most common form</p> $\nabla \times \vec{E} = -j\omega \vec{P}$ $\nabla \times \vec{H} = \vec{J} + j\omega \vec{D}$

Constitutive Relations: $\vec{D} = \epsilon \vec{E}$ $\vec{B} = \mu \vec{H}$

Lorentz Force Law: $\vec{F} = Q\vec{E} + Q(\vec{u} \times \vec{B})$

Maxwell's Equations for Static Fields

	Integral Form	Differential Form
Time-Domain	$\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_v dv$ <p style="text-align: center;">Most general form</p> $\oiint_S \vec{B} \cdot d\vec{s} = 0$ $\oint_L \vec{E} \cdot d\vec{\ell} = 0$ $\oint_L \vec{H} \cdot d\vec{\ell} = \iint_S \vec{J} \cdot d\vec{s}$	$\nabla \cdot \vec{D} = \rho_v$ $\nabla \cdot \vec{B} = 0$ $\nabla \times \vec{E} = 0$ $\nabla \times \vec{H} = \vec{J}$
Frequency-Domain	$\oiint_S \vec{D} \cdot d\vec{s} = \iiint_V \rho_v dv$ $\oiint_S \vec{B} \cdot d\vec{s} = 0$ $\oint_L \vec{E} \cdot d\vec{\ell} = 0$ $\oint_L \vec{H} \cdot d\vec{\ell} = \iint_S \vec{J} \cdot d\vec{s}$	$\nabla \cdot \vec{D} = \rho_v$ $\nabla \cdot \vec{B} = 0$ <p style="text-align: center;">Most common form</p> $\nabla \times \vec{E} = 0$ $\nabla \times \vec{H} = \vec{J}$

Constitutive Relations: $\vec{D} = \epsilon \vec{E}$ $\vec{B} = \mu \vec{H}$

Lorentz Force Law: $\vec{F} = Q\vec{E} + Q(\vec{u} \times \vec{B})$

Electric and Magnetic Fields are Decoupled

After observing the results on the previous slide, Maxwell's equations have decoupled into two independent sets of equations. One set describes *electrostatics* and the other describes *magnetostatics*.

Electrostatics

$$\begin{aligned} \oiint_S \vec{D} \cdot d\vec{s} &= \iiint_V \rho_v dv & \nabla \cdot \vec{D} &= \rho_v \\ \oint_L \vec{E} \cdot d\vec{\ell} &= 0 & \nabla \times \vec{E} &= 0 \\ \vec{D} &= \epsilon \vec{E} & \vec{F} &= Q\vec{E} \end{aligned}$$

- Charges must be present to get a nontrivial solution.
- $\nabla \times \vec{E} = 0$ says \vec{E} is irrotational and forms mostly straight lines.
- The electric fields are not affected by permeability.

Magnetostatics

$$\begin{aligned} \oiint_S \vec{B} \cdot d\vec{s} &= 0 & \nabla \cdot \vec{B} &= 0 \\ \oint_L \vec{H} \cdot d\vec{\ell} &= \iint_S \vec{J} \cdot d\vec{s} & \nabla \times \vec{H} &= \vec{J} \\ \vec{B} &= \mu \vec{H} & \vec{F} &= Q(\vec{u} \times \vec{B}) \end{aligned}$$

- Current must be present to get a nontrivial solution.
- $\nabla \cdot \vec{B} = 0$ says \vec{B} is solenoidal and forms loops.
- The magnetic fields are not affected by permittivity.