



Computational Science:
Introduction to Finite-Difference Time-Domain

Advanced FDTD Algorithms

Lecture Outline

- Alternating-Direction-Implicit (ADI) Algorithm
- Pseudospectral Time-Domain (PSTD)
- M24 Algorithm
 - Introduction
 - Formulation
 - Performance Improvement

Alternating-Direction-Implicit Algorithm

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Some Limitations of Ordinary FDTD

Recall the Courant Stability Condition...

$$\Delta t \leq \frac{1}{c_0 \sqrt{\frac{1}{(\Delta x)^2} + \frac{1}{(\Delta y)^2} + \frac{1}{(\Delta z)^2}}} \cong \frac{\Delta_{\min}}{c_0 \sqrt{3}}$$

Problem – If the cell size is much less than the wavelength, then a prohibitively large number of iterations will be required due to the extremely small time step that ensures stability.

- Low-frequency bioelectromagnetics
- Simulation of VLSI circuits

It is desired to exceed the Courant limit by more than 10×.

How?

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New Stability Condition

In an alternating-direction-implicit (ADI) algorithm, the grid resolution no longer needs to be considered. Only the cycle time of the highest frequency matters.

$$\Delta t \leq \frac{\tau_{\min}}{N_{\tau}} \quad \tau_{\min} = \frac{1}{f_{\max}} \quad N_{\tau} \geq 20$$

Simulations can get away with extremely fine grid resolution without having to reduce Δt for stability! ☺

ADI-FDTD is unconditionally stable, but this does not mean unconditionally accurate.

Alternating Direction Implicit Method

Suppose we have the following PDE:

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

Up until now, this was solved using the Crank-Nicolson scheme

$$\frac{u_{n+1}^{i,j} - u_n^{i,j}}{\Delta t} = \frac{\partial^2 (u_{n+1}^{i,j} + u_n^{i,j})}{\partial x^2} + \frac{\partial^2 (u_{n+1}^{i,j} + u_n^{i,j})}{\partial y^2}$$

Instead, now this solution is split into two time-steps, each of duration $\Delta t/2$.

$$n \rightarrow n+1/2: \quad \frac{u_{n+1/2}^{i,j} - u_n^{i,j}}{\Delta t/2} = \frac{\partial^2 u_{n+1/2}^{i,j}}{\partial x^2} + \frac{\partial^2 u_n^{i,j}}{\partial y^2}$$

$$n+1/2 \rightarrow n+1: \quad \frac{u_{n+1}^{i,j} - u_{n+1/2}^{i,j}}{\Delta t/2} = \frac{\partial^2 u_{n+1/2}^{i,j}}{\partial x^2} + \frac{\partial^2 u_{n+1}^{i,j}}{\partial y^2}$$

Zheng/Chen/Zhang ADI Algorithm

Spatial Derivatives: Fields are staggered on an ordinary Yee grid.

Time Derivatives: Fields are collocated in time.

Original Finite-Difference Equation:

$$\frac{E_x|_{n+1}^{i+1/2,j,k} - E_x|_n^{i+1/2,j,k}}{\Delta t} = \frac{1}{\epsilon} \left(\frac{H_z|_{n+1/2}^{i+1/2,j+1/2,k} - H_z|_{n+1/2}^{i+1/2,j-1/2,k}}{\Delta y} - \frac{H_y|_{n+1/2}^{i+1/2,j,k+1/2} - H_y|_{n+1/2}^{i+1/2,j,k-1/2}}{\Delta z} \right)$$

ADI Finite-Difference Equations (now two steps):

$$\frac{E_x|_{n+1/2}^{i+1/2,j,k} - E_x|_n^{i+1/2,j,k}}{\Delta t/2} = \frac{1}{\epsilon} \left(\frac{H_z|_{n+1/2}^{i+1/2,j+1/2,k} - H_z|_{n+1/2}^{i+1/2,j-1/2,k}}{\Delta y} - \frac{H_y|_n^{i+1/2,j,k+1/2} - H_y|_n^{i+1/2,j,k-1/2}}{\Delta z} \right)$$

$$\frac{E_x|_{n+1}^{i+1/2,j,k} - E_x|_{n+1/2}^{i+1/2,j,k}}{\Delta t/2} = \frac{1}{\epsilon} \left(\frac{H_z|_{n+1/2}^{i+1/2,j+1/2,k} - H_z|_{n+1/2}^{i+1/2,j-1/2,k}}{\Delta y} - \frac{H_y|_{n+1}^{i+1/2,j,k+1/2} - H_y|_{n+1}^{i+1/2,j,k-1/2}}{\Delta z} \right)$$



Never calculated

Not calculated yet

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Complete Set of Split Finite-Difference Equations

Subiteration #1

$$E_x|_{n+1/2}^{i,j,k} = E_x|_{n+1/2}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_z|_{n+1/2}^{i,j+1/2,k} - H_z|_{n+1/2}^{i,j-1/2,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_y|_{n+1/2}^{i,j,k+1/2} - H_y|_{n+1/2}^{i,j,k-1/2}) \quad (4.99a)$$

$$E_y|_{n+1/2}^{i,j,k} = E_y|_{n+1/2}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x|_{n+1/2}^{i+1/2,j,k} - H_x|_{n+1/2}^{i-1/2,j,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_z|_{n+1/2}^{i,j+1/2,k} - H_z|_{n+1/2}^{i,j-1/2,k}) \quad (4.99b)$$

$$E_z|_{n+1/2}^{i,j,k} = E_z|_{n+1/2}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x|_{n+1/2}^{i+1/2,j,k} - H_x|_{n+1/2}^{i-1/2,j,k}) - \frac{\Delta t}{2\epsilon\Delta y} (H_y|_{n+1/2}^{i,j,k+1/2} - H_y|_{n+1/2}^{i,j,k-1/2}) \quad (4.99c)$$

$$H_x|_{n+1/2}^{i,j,k+1/2} = H_x|_{n+1/2}^{i,j,k+1/2} + \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1/2}^{i,j,k+1} - E_y|_{n+1/2}^{i,j,k}) - \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1/2}^{i,j,k+1/2} - E_z|_{n+1/2}^{i,j,k}) \quad (4.100a)$$

$$H_x|_{n+1/2}^{i,j,k-1/2} = H_x|_{n+1/2}^{i,j,k-1/2} + \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1/2}^{i,j,k+1/2} - E_y|_{n+1/2}^{i,j,k}) - \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1/2}^{i,j,k+1/2} - E_z|_{n+1/2}^{i,j,k}) \quad (4.100b)$$

$$H_x|_{n+1/2}^{i,j+1/2,k} = H_x|_{n+1/2}^{i,j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1/2}^{i,j+1/2,k+1} - E_z|_{n+1/2}^{i,j+1/2,k}) - \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1/2}^{i,j+1/2,k} - E_y|_{n+1/2}^{i,j,k}) \quad (4.100c)$$

Subiteration #2

$$E_x|_{n+1}^{i,j,k} = E_x|_{n+1}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_z|_{n+1}^{i,j+1/2,k} - H_z|_{n+1}^{i,j-1/2,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_y|_{n+1}^{i,j,k+1/2} - H_y|_{n+1}^{i,j,k-1/2}) \quad (4.101a)$$

$$E_y|_{n+1}^{i,j,k} = E_y|_{n+1}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x|_{n+1}^{i+1/2,j,k} - H_x|_{n+1}^{i-1/2,j,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_z|_{n+1}^{i,j+1/2,k} - H_z|_{n+1}^{i,j-1/2,k}) \quad (4.101b)$$

$$E_z|_{n+1}^{i,j,k} = E_z|_{n+1}^{i,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x|_{n+1}^{i+1/2,j,k} - H_x|_{n+1}^{i-1/2,j,k}) - \frac{\Delta t}{2\epsilon\Delta y} (H_y|_{n+1}^{i,j,k+1/2} - H_y|_{n+1}^{i,j,k-1/2}) \quad (4.101c)$$

$$H_x|_{n+1}^{i,j,k+1/2} = H_x|_{n+1}^{i,j,k+1/2} + \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1}^{i,j,k+1} - E_y|_{n+1}^{i,j,k}) - \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1}^{i,j,k+1/2} - E_z|_{n+1}^{i,j,k}) \quad (4.101d)$$

$$H_x|_{n+1}^{i,j,k-1/2} = H_x|_{n+1}^{i,j,k-1/2} + \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1}^{i,j,k+1/2} - E_y|_{n+1}^{i,j,k}) - \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1}^{i,j,k+1/2} - E_z|_{n+1}^{i,j,k}) \quad (4.101e)$$

$$H_x|_{n+1}^{i,j+1/2,k} = H_x|_{n+1}^{i,j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1}^{i,j+1/2,k+1} - E_z|_{n+1}^{i,j+1/2,k}) - \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1}^{i,j+1/2,k} - E_y|_{n+1}^{i,j,k}) \quad (4.101f)$$

$$H_x|_{n+1}^{i,j-1/2,k} = H_x|_{n+1}^{i,j-1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_z|_{n+1}^{i,j+1/2,k} - E_z|_{n+1}^{i,j,k}) - \frac{\Delta t}{2\mu\Delta z} (E_y|_{n+1}^{i,j-1/2,k} - E_y|_{n+1}^{i,j,k}) \quad (4.101g)$$



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Derivation of ADI Update Equations (1 of 2)

Subiteration #1

$$E_{x|n+1/2,j,k}^{[n+1/2]} = E_{x|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\epsilon\Delta y} (H_{y|n+1/2,j+1/2,k}^{[n+1/2]} - H_{y|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta x} (H_{z|n+1/2,j+1/2,k}^{[n+1/2]} - H_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.99a)$$

$$E_{y|n+1/2,j,k}^{[n+1/2]} = E_{y|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\epsilon\Delta x} (H_{x|n+1/2,j+1/2,k}^{[n+1/2]} - H_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta z} (H_{z|n+1/2,j+1/2,k}^{[n+1/2]} - H_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.99b)$$

$$E_{z|n+1/2,j,k}^{[n+1/2]} = E_{z|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\epsilon\Delta x} (H_{x|n+1/2,j+1/2,k}^{[n+1/2]} - H_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta y} (H_{y|n+1/2,j+1/2,k}^{[n+1/2]} - H_{y|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.99c)$$

$$H_{x|n+1/2,j,k}^{[n+1/2]} = H_{x|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\mu\Delta z} (E_{y|n+1/2,j+1/2,k}^{[n+1/2]} - E_{y|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta y} (E_{z|n+1/2,j+1/2,k}^{[n+1/2]} - E_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.100a)$$

$$H_{y|n+1/2,j,k}^{[n+1/2]} = H_{y|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\mu\Delta z} (E_{z|n+1/2,j+1/2,k}^{[n+1/2]} - E_{z|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta x} (E_{x|n+1/2,j+1/2,k}^{[n+1/2]} - E_{x|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.100b)$$

$$H_{z|n+1/2,j,k}^{[n+1/2]} = H_{z|n+1/2,j,k}^{[n]} + \frac{\Delta t}{2\mu\Delta y} (E_{x|n+1/2,j+1/2,k}^{[n+1/2]} - E_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta x} (E_{y|n+1/2,j+1/2,k}^{[n+1/2]} - E_{y|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.100c)$$

Substitute Eq. (4.100) into Eq. (4.99) to eliminate the \vec{H} fields at the $n + 1/2$ time steps.
Retain Eq. (4.100).

Derivation of ADI Update Equations (2 of 2)

Subiteration #2

$$E_{x|n+1/2,j,k}^{[n+1]} = E_{x|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\epsilon\Delta y} (H_{y|n+1/2,j+1/2,k}^{[n+1/2]} - H_{y|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta x} (H_{z|n+1/2,j+1/2,k}^{[n+1/2]} - H_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.101a)$$

$$E_{y|n+1/2,j,k}^{[n+1]} = E_{y|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\epsilon\Delta x} (H_{x|n+1/2,j+1/2,k}^{[n+1/2]} - H_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta z} (H_{z|n+1/2,j+1/2,k}^{[n+1/2]} - H_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.101b)$$

$$E_{z|n+1/2,j,k}^{[n+1]} = E_{z|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\epsilon\Delta x} (H_{x|n+1/2,j+1/2,k}^{[n+1/2]} - H_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\epsilon\Delta y} (H_{y|n+1/2,j+1/2,k}^{[n+1/2]} - H_{y|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.101c)$$

$$H_{x|n+1/2,j,k}^{[n+1]} = H_{x|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\mu\Delta z} (E_{y|n+1/2,j+1/2,k}^{[n+1/2]} - E_{y|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta y} (E_{z|n+1/2,j+1/2,k}^{[n+1/2]} - E_{z|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.102a)$$

$$H_{y|n+1/2,j,k}^{[n+1]} = H_{y|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\mu\Delta z} (E_{z|n+1/2,j+1/2,k}^{[n+1/2]} - E_{z|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta x} (E_{x|n+1/2,j+1/2,k}^{[n+1/2]} - E_{x|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.102b)$$

$$H_{z|n+1/2,j,k}^{[n+1]} = H_{z|n+1/2,j,k}^{[n+1/2]} + \frac{\Delta t}{2\mu\Delta y} (E_{x|n+1/2,j+1/2,k}^{[n+1/2]} - E_{x|n+1/2,j-1/2,k}^{[n+1/2]}) - \frac{\Delta t}{2\mu\Delta x} (E_{y|n+1/2,j+1/2,k}^{[n+1/2]} - E_{y|n+1/2,j-1/2,k}^{[n+1/2]}) \quad (4.102c)$$

Substitute Eq. (4.102) into Eq. (4.101) to eliminate the \vec{H} fields at the $n + 1$ time steps.
Retain Eq. (4.102).

ADI Finite-Difference Equations

Subiteration #1

$$E_x^{n+1/2,j,k} = E_x^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k} - H_x^{n+1/2,j-1/2,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j,k+1/2} - H_x^{n+1/2,j,k-1/2}) \quad (4.99a)$$

$$E_y^{n+1/2,j,k} = E_y^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.99b)$$

$$E_z^{n+1/2,j,k} = E_z^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.99c)$$

$$H_x^{n+1/2,j+1/2,k} = H_x^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta z} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta y} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j-1/2,k+1/2}) \quad (4.100a)$$

$$H_y^{n+1/2,j+1/2,k} = H_y^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta x} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta z} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j-1/2,k+1/2}) \quad (4.100b)$$

$$H_z^{n+1/2,j+1/2,k} = H_z^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta x} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j-1/2,k+1/2}) \quad (4.100c)$$

Subiteration #2

$$E_x^{n+1,j,k} = E_x^{n+1/2,j,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k} - H_x^{n+1/2,j-1/2,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j,k+1/2} - H_x^{n+1/2,j,k-1/2}) \quad (4.101a)$$

$$E_y^{n+1,j,k} = E_y^{n+1/2,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.101b)$$

$$E_z^{n+1,j,k} = E_z^{n+1/2,j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.101c)$$

$$H_x^{n+1,j+1/2,k} = H_x^{n+1/2,j+1/2,k} + \frac{\Delta t}{2\mu\Delta z} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta y} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j-1/2,k+1/2}) \quad (4.101d)$$

$$H_y^{n+1,j+1/2,k} = H_y^{n+1/2,j+1/2,k} + \frac{\Delta t}{2\mu\Delta x} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta z} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j-1/2,k+1/2}) \quad (4.101e)$$

$$H_z^{n+1,j+1/2,k} = H_z^{n+1/2,j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta x} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j-1/2,k+1/2}) \quad (4.101f)$$

Note: the \vec{H} field update equations remain unchanged.



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Solution to ADI Finite-Difference Equations (1 of 2)

Subiteration #1

$$E_x^{n+1/2,j,k} = E_x^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k} - H_x^{n+1/2,j-1/2,k}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j,k+1/2} - H_x^{n+1/2,j,k-1/2}) \quad (4.99a)$$

$$E_y^{n+1/2,j,k} = E_y^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta z} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.99b)$$

$$E_z^{n+1/2,j,k} = E_z^n{}_{j,k} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\epsilon\Delta y} (H_x^{n+1/2,j+1/2,k+1/2} - H_x^{n+1/2,j-1/2,k+1/2}) \quad (4.99c)$$

$$H_x^{n+1/2,j+1/2,k} = H_x^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta z} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta y} (E_y^{n+1/2,j+1/2,k+1/2} - E_y^{n+1/2,j-1/2,k+1/2}) \quad (4.100a)$$

$$H_y^{n+1/2,j+1/2,k} = H_y^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta x} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta z} (E_z^{n+1/2,j+1/2,k+1/2} - E_z^{n+1/2,j-1/2,k+1/2}) \quad (4.100b)$$

$$H_z^{n+1/2,j+1/2,k} = H_z^n{}_{j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j+1/2,k-1/2}) - \frac{\Delta t}{2\mu\Delta x} (E_x^{n+1/2,j+1/2,k+1/2} - E_x^{n+1/2,j-1/2,k+1/2}) \quad (4.100c)$$

This equation is written once for each occurrence of E_x at a constant position j .

This set of equations has the form of a tridiagonal matrix and is easily solved.

This equation is written once for each occurrence of E_y at a constant position k .

This set of equations has the form of a tridiagonal matrix and is easily solved.

This equation is written once for each occurrence of E_z at a constant position i .

This set of equations has the form of a tridiagonal matrix and is easily solved.



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Solution to ADI Finite-Difference Equations (2 of 2)

Subiteration #2

This equation is written once for each occurrence of E_x at a constant position k .

This set of equations has the form of a tridiagonal matrix and is easily solved.

This equation is written once for each occurrence of E_y at a constant position i .

This set of equations has the form of a tridiagonal matrix and is easily solved.

This equation is written once for each occurrence of E_z at a constant position j .

This set of equations has the form of a tridiagonal matrix and is easily solved.

$$\begin{aligned}
 E_x^{[n+1]}_{l,j+1/2,k} &= E_x^{[n+1/2]}_{l,j+1/2,k} + \frac{\Delta t}{2\epsilon\Delta y} (H_z^{[n+1/2]}_{l,j+1/2,k} - H_z^{[n+1/2]}_{l,j+1/2,k-1}) \\
 &\quad - \frac{\Delta t}{2\epsilon\Delta x} (H_z^{[n+1]}_{l,j+1/2,k+1/2} - H_z^{[n+1]}_{l,j+1/2,k-1/2}) \tag{4.101a} \\
 E_x^{[n+1]}_{l,j+1/2,k} &= E_y^{[n+1/2]}_{l,j+1/2,k} + \frac{\Delta t}{2\epsilon\Delta z} (H_z^{[n+1/2]}_{l,j+1/2,k+1/2} - H_z^{[n+1/2]}_{l,j+1/2,k-1/2}) \\
 &\quad - \frac{\Delta t}{2\epsilon\Delta x} (H_z^{[n+1]}_{l,j+1/2,j+1/2,k} - H_z^{[n+1]}_{l,j-1/2,j+1/2,k}) \\
 E_y^{[n+1]}_{l,j,k+1/2} &= E_y^{[n+1/2]}_{l,j,k+1/2} + \frac{\Delta t}{2\epsilon\Delta x} (H_x^{[n+1/2]}_{l,j+1/2,j,k+1/2} - H_x^{[n+1/2]}_{l,j-1/2,j,k+1/2}) \\
 &\quad - \frac{\Delta t}{2\epsilon\Delta y} (H_x^{[n+1]}_{l,j+1/2,k+1/2} - H_x^{[n+1]}_{l,j-1/2,k+1/2}) \\
 H_z^{[n+1]}_{l,j+1/2,k+1/2} &= H_z^{[n+1/2]}_{l,j+1/2,k+1/2} + \frac{\Delta t}{2\mu\Delta z} (E_y^{[n+1/2]}_{l,j+1/2,k+1} - E_y^{[n+1/2]}_{l,j,k+1}) \\
 &\quad - \frac{\Delta t}{2\mu\Delta y} (E_x^{[n+1]}_{l,j+1,k+1/2} - E_x^{[n+1]}_{l,j,k+1/2}) \\
 H_z^{[n+1]}_{l,j+1/2,j,k+1/2} &= H_y^{[n+1/2]}_{l,j+1/2,j,k+1/2} + \frac{\Delta t}{2\mu\Delta x} (E_x^{[n+1/2]}_{l,j+1/2,k+1/2} - E_x^{[n+1/2]}_{l,j,k+1/2}) \\
 &\quad - \frac{\Delta t}{2\mu\Delta z} (E_x^{[n+1]}_{l,j+1/2,j,k+1} - E_x^{[n+1]}_{l,j+1/2,j,k}) \\
 H_z^{[n+1]}_{l,j+1/2,j+1/2,k} &= H_z^{[n+1/2]}_{l,j+1/2,j+1/2,k} + \frac{\Delta t}{2\mu\Delta y} (E_x^{[n+1/2]}_{l,j+1/2,j+1,k} - E_x^{[n+1/2]}_{l,j,k+1/2}) \\
 &\quad - \frac{\Delta t}{2\mu\Delta x} (E_y^{[n+1]}_{l,j+1,j+1/2,k} - E_y^{[n+1]}_{l,j+1/2,j,k})
 \end{aligned}$$



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Notes in ADI-FDTD

- ADI-FDTD is unconditionally stable for all Δt so the Courant stability condition no longer applies.
- ADI-FDTD has accuracy issues.
 - Dispersion error increases steadily above the Courant stability condition.
 - Increasing error with increasing Δt .
- ADI-FDTD not well suited for electrically-large simulations.
- Best applied to electrically-small problems requiring very fine grids.



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Pseudospectral Time-Domain

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Purpose of PSTD

Numerical dispersion is a serious problem that is particularly severe in electrically large simulations.

It arises due to the numerical error arising from approximating the spatial derivatives in Maxwell's equations.

Spectral accuracy is achieved when the fields are represented by trigonometric functions or Chebyshev polynomials. This means numerical dispersion decreases exponentially with sampling density.

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Options for Approximating Spatial Derivatives

Finite-Difference Approximation

$$\frac{df_i}{dx} \cong \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$

Requires a minimum of 10 to 20 points per wavelength.

Fourier (Trigonometric) Approximation

$$\frac{df}{dx} \cong \frac{2\pi}{N\Delta x} \text{FFT}^{-1} \left\{ (jn) \text{FFT} \{f\} \right\}$$

Requires a minimum of 2 points per wavelength.

Chebyshev Approximation

Requires a minimum of π points per wavelength.

Achieving Spectral Accuracy

Single-Domain PSTD

Internal medium must be continuously inhomogeneous.



Multidomain PSTD

When the internal medium is piecewise inhomogeneous, single-domain is applied to each subdomain and then matched at the boundaries.

Notes

Wraparound Effect

When trigonometric functions are used, the grid becomes inherently periodic. This can be mitigated by using a PML at the boundaries.

Gibb's Phenomenon

When the field has discontinuities, like at a boundary of an object, a significant overshoot and ringing is introduced in the vicinity of the boundary.

M24 Algorithm

Data and diagrams in this section were borrowed from

M. F. Hadi, M. Picket-May, "A Modified FDTD (2,4) Scheme for Modeling Electrically Large Structures with High-Phase Accuracy," IEEE Trans. on Ant. and Prop., Vol. 45, No. 2, pp. 254-264, 1997.

Why M24?

- Problem – excessive phase error that accumulates during an FDTD simulation.
- Waves on a grid propagate differently than physical waves.
- Particularly severe for large structures.
- (2,4) scheme means 2nd-order differences in time and 4th-order differences in space.
- (4,4) scheme means 4th-order differences in time and 4th-order differences in space.
- These higher order schemes suffer from instability and more complicated boundary conditions.

Notation

- $L\#_1\#_2$
 - L algorithm (S=standard, M=modified)
 - $\#_1$ order of accuracy in time
 - $\#_2$ order of accuracy in space
- S22 – Standard FDTD with 2nd-order differences in time and 2nd-order differences in space. This is what we learned this semester.
- S24, S44 – Improved formulations, but with some problems.
- M24 – Modified FDTD with 2nd-order differences in time and 4th-order differences in space. Currently state-of-the-art.

S24 Update Equation (1 of 2)

Recall the S22 update equation for E_z .

$$\frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \left(\frac{c_0}{\epsilon_{zz}|^{i,j}} \right) \left(\frac{H_y|_{t+\frac{\Delta x}{2}}^{i,j} - H_y|_{t+\frac{\Delta x}{2}}^{i-1,j}}{\Delta x} - \frac{H_x|_{t+\frac{\Delta y}{2}}^{i,j} - H_x|_{t+\frac{\Delta y}{2}}^{i,j-1}}{\Delta y} \right)$$

A similar equation can be written, but with 4th-order accurate finite-differences.

$$\frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \left(\frac{c_0}{\epsilon_{zz}|^{i,j}} \right) \left(\frac{-H_y|_{t+\frac{\Delta x}{2}}^{i+1,j} + 27H_y|_{t+\frac{\Delta x}{2}}^{i,j} - 27H_y|_{t+\frac{\Delta x}{2}}^{i-1,j} + H_y|_{t+\frac{\Delta x}{2}}^{i-2,j}}{24\Delta x} - \frac{-H_x|_{t+\frac{\Delta y}{2}}^{i,j+1} + 27H_x|_{t+\frac{\Delta y}{2}}^{i,j} - 27H_x|_{t+\frac{\Delta y}{2}}^{i,j-1} + H_x|_{t+\frac{\Delta y}{2}}^{i,j-2}}{24\Delta y} \right)$$

Rearrange S24 Update Equation

For simplicity, let $h = \Delta x = \Delta y$

$$\left(\frac{\epsilon_{zz}|^{i,j}}{c_0} \right) \frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \frac{1}{24h} \left(\begin{aligned} &-H_y|_{t+\frac{h}{2}}^{i+1,j} + 27H_y|_{t+\frac{h}{2}}^{i,j} - 27H_y|_{t+\frac{h}{2}}^{i-1,j} + H_y|_{t+\frac{h}{2}}^{i-2,j} \\ &+ H_x|_{t+\frac{h}{2}}^{i,j+1} - 27H_x|_{t+\frac{h}{2}}^{i,j} + 27H_x|_{t+\frac{h}{2}}^{i,j-1} - H_x|_{t+\frac{h}{2}}^{i,j-2} \end{aligned} \right)$$

The right hand side can be rearranged as follows

$$\left(\frac{\epsilon_{zz}|^{i,j}}{c_0} \right) \frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \frac{H_x|_{t+\frac{h}{2}}^{i,j+1} - H_x|_{t+\frac{h}{2}}^{i,j-2} - H_y|_{t+\frac{h}{2}}^{i+1,j} + H_y|_{t+\frac{h}{2}}^{i-2,j}}{24h} + \frac{-27H_x|_{t+\frac{h}{2}}^{i,j} + 27H_x|_{t+\frac{h}{2}}^{i,j-1} + 27H_y|_{t+\frac{h}{2}}^{i,j} - 27H_y|_{t+\frac{h}{2}}^{i-1,j}}{24h}$$

$$\left(\frac{\epsilon_{zz}|^{i,j}}{c_0} \right) \frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \frac{9}{8h} \left(-H_x|_{t+\frac{h}{2}}^{i,j} + H_x|_{t+\frac{h}{2}}^{i,j-1} + H_y|_{t+\frac{h}{2}}^{i,j} - H_y|_{t+\frac{h}{2}}^{i-1,j} \right) - \frac{1}{24h} \left(-H_x|_{t+\frac{h}{2}}^{i,j+1} + H_x|_{t+\frac{h}{2}}^{i,j-2} + H_y|_{t+\frac{h}{2}}^{i+1,j} - H_y|_{t+\frac{h}{2}}^{i-2,j} \right)$$

$$\left(\frac{\epsilon_{zz}|^{i,j}}{c_0} \right) \frac{\tilde{E}_z|_{t+\Delta t}^{i,j} - \tilde{E}_z|_t^{i,j}}{\Delta t} = \frac{9}{8h^2} \left(-hH_x|_{t+\frac{h}{2}}^{i,j} + hH_x|_{t+\frac{h}{2}}^{i,j-1} + hH_y|_{t+\frac{h}{2}}^{i,j} - hH_y|_{t+\frac{h}{2}}^{i-1,j} \right) - \frac{1}{8(9h^2)} \left(3hH_x|_{t+\frac{h}{2}}^{i,j+1} - 3hH_x|_{t+\frac{h}{2}}^{i,j-2} - 3hH_y|_{t+\frac{h}{2}}^{i+1,j} + 3hH_y|_{t+\frac{h}{2}}^{i-2,j} \right)$$

S24 Contains Closed Contour Line Integrals

Observe that the right hand side of the new finite-difference equation has two expressions in the form of closed contour line integrals.

$$\left(\frac{\epsilon_z}{c_0}\right) \frac{\tilde{E}_z|_{i+M}^{j,J} - \tilde{E}_z|_i^{j,J}}{\Delta t} = \frac{9}{8h^2} \left(-hH_x|_{i+\frac{M}{2}}^{j,J} + hH_x|_{i+\frac{M}{2}}^{j,J-1} + hH_y|_{i+\frac{M}{2}}^{j,J} - hH_y|_{i+\frac{M}{2}}^{j,J-1}\right) - \frac{1}{8(9h^2)} \left(3hH_x|_{i+\frac{M}{2}}^{j,J+1} - 3hH_x|_{i+\frac{M}{2}}^{j,J-2} - 3hH_y|_{i+\frac{M}{2}}^{j,J+1} + 3hH_y|_{i+\frac{M}{2}}^{j,J-2}\right)$$

$$\left(\frac{\epsilon_z}{c_0}\right) \frac{\partial \tilde{E}_z}{\partial t} = \frac{9}{8h^2} \oint_{C_1} \vec{H} \cdot d\vec{\ell} - \frac{1}{8(9h^2)} \oint_{C_2} \vec{H} \cdot d\vec{\ell}$$

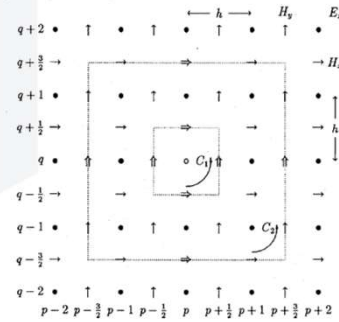


Fig. 1. The modified Ampere's law applied on Yee's TM lattice using two concentric loops.

Maxwell's Equations in Integral Form

Recall Maxwell's equations in integral form

$$\begin{aligned} \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} & \oint_L \vec{E} \cdot d\vec{\ell} &= -\frac{\partial}{\partial t} \iint_S \vec{B} \cdot d\vec{s} \\ \nabla \times \vec{H} &= \frac{\partial \vec{D}}{\partial t} & \oint_L \vec{H} \cdot d\vec{\ell} &= \frac{\partial}{\partial t} \iint_S \vec{D} \cdot d\vec{s} \end{aligned}$$

These equations let the line integrals be calculated as surface integrals.

Use Surface Integral Instead of Line Integral

Calculate the line integrals by instead calculating the surface integrals over the area enclosed by each contour.

$$\begin{aligned}
 \oint_{C_1} \vec{H} \cdot d\vec{\ell} &= \frac{\partial}{\partial t} \iint_{S_1} \vec{D} \cdot d\vec{s} & \oint_{C_2} \vec{H} \cdot d\vec{\ell} &= \epsilon_{zz} \frac{\partial E_z}{\partial t} \iint_{S_2} ds \\
 &= \frac{\partial}{\partial t} \iint_{S_1} \epsilon \vec{E} \cdot d\vec{s} & &= \epsilon_{zz} \frac{\partial E_z}{\partial t} (3h)^2 \\
 &= \epsilon_{zz} \frac{\partial}{\partial t} \iint_{S_1} E_z ds & &= 9\epsilon_{zz} h^2 \frac{\partial E_z}{\partial t} \\
 &= \epsilon_{zz} \frac{\partial E_z}{\partial t} \iint_{S_1} ds & & \\
 &= \epsilon_{zz} \frac{\partial E_z}{\partial t} h^2 & & \\
 &= \epsilon_{zz} \epsilon h^2 \frac{\partial E_z}{\partial t} & &
 \end{aligned}$$

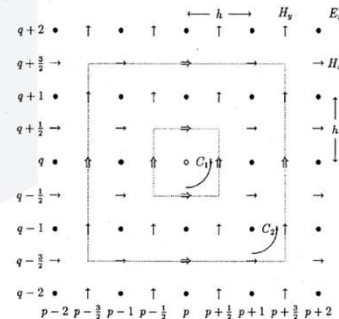


Fig. 1. The modified Ampere's law applied on Yee's TM lattice using two concentric loops.

Compile New Equation

We start with the S24 equation derived with line integrals.

$$\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} = \frac{9}{8h^2} \oint_{C_1} \vec{H} \cdot d\vec{\ell} - \frac{1}{8(9h^2)} \oint_{C_2} \vec{H} \cdot d\vec{\ell}$$

Replace the line integrals with the new surface integrals.

$$\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} = \frac{9}{8h^2} \left[\epsilon_{zz} h^2 \frac{\partial E_z}{\partial t} \right]_{C_1} - \frac{1}{8(9h^2)} \left[9\epsilon_{zz} h^2 \frac{\partial E_z}{\partial t} \right]_{C_2}$$

Now simplify.

$$\left[\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = \frac{9}{8} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} - \frac{1}{8} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2}$$

Observe that this is just a weighted sum of two applications of Ampere's circuit law.

The coefficients add up to unity ($-1/8 + 9/8 = 1$) so that the integrity of Maxwell's equations is preserved.

Split The Outer Loop

Here, the outer loop is split into two distinct loops.

Note, half of the terms are included in the first outer loop and the remaining are included in the second outer loop.

$$\left[\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = \frac{9}{8} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} - \frac{1}{8} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2}$$

$$\left[\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = \frac{9}{8} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} - \frac{1}{16} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2} - \frac{1}{16} \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_3}$$

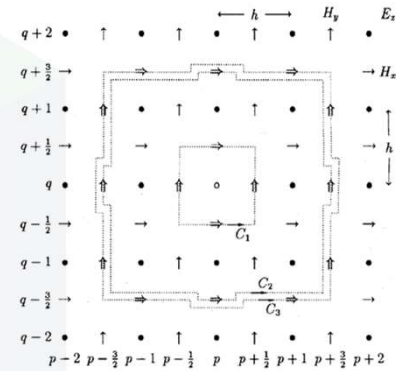


Fig. 2. Assigning the eight diagonal field nodes to their own separate loop serves to increase the ϵ_{zz} -bandwidth of the M24 scheme.

Assign Arbitrary Weights

More degrees of freedom are needed in order to reduce numerical error.

To obtain these degrees of freedom, assign arbitrary weights to the terms in our equation.

$$\left[\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = K_3 \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} + K_1 \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2} + K_2 \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_3}$$

Note that in order to preserve the integrity of Maxwell's equations, it is required that $K_1 + K_2 + K_3 = 1$. To enforce this, the equation is written as

$$\left[\left(\frac{\epsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = (1 - K_1 - K_2) \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} + K_1 \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2} + K_2 \left[\epsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_3}$$

M24 Update Equation for Ez (1 of 2)

Starting with

$$\left[\left(\frac{\varepsilon_{zz}}{c_0} \right) \frac{\partial \tilde{E}_z}{\partial t} \right]_{\text{FDTD}} = (1 - K_1 - K_2) \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} + K_1 \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2} + K_2 \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_3}$$

Each term on the right is calculated as...

$$\begin{aligned} \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_1} &= \frac{1}{h} \left(-H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j} + H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j-1} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i,j} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i-1,j} \right) \\ \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_2} &= \frac{1}{3h} \left(H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j+1} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j-2} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i+1,j} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j} \right) \\ \left[\varepsilon_{zz} \frac{\partial E_z}{\partial t} \right]_{C_3} &= \frac{1}{6h} \left(H_x \Big|_{t+\frac{\Delta t}{2}}^{i-1,j-2} + H_x \Big|_{t+\frac{\Delta t}{2}}^{i+1,j-2} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i-1,j+1} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i+1,j+1} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i+1,j-1} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j-1} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j+1} \right) \end{aligned}$$

M24 Update Equation for Ez (2 of 2)

So the overall update equation is now

$$\begin{aligned} \left(\frac{\varepsilon_{zz}}{c_0} \Big|_{t+\Delta t}^{i,j} \right) \frac{\tilde{E}_z \Big|_{t+\Delta t}^{i,j} - \tilde{E}_z \Big|_t^{i,j}}{\Delta t} &= \left(\frac{1 - K_1 - K_2}{h} \right) \left(-H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j} + H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j-1} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i,j} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i-1,j} \right) \\ &+ \frac{K_1}{3h} \left(H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j+1} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i,j-2} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i+1,j} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j} \right) \\ &+ \frac{K_2}{6h} \left(H_x \Big|_{t+\frac{\Delta t}{2}}^{i-1,j-2} + H_x \Big|_{t+\frac{\Delta t}{2}}^{i+1,j-2} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i-1,j+1} - H_x \Big|_{t+\frac{\Delta t}{2}}^{i+1,j+1} \right. \\ &\quad \left. + H_y \Big|_{t+\frac{\Delta t}{2}}^{i+1,j-1} + H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j-1} - H_y \Big|_{t+\frac{\Delta t}{2}}^{i-2,j+1} \right) \end{aligned}$$

Optimum Values for K_1 and K_2

TABLE I
OPTIMUM VALUES FOR K_1 AND K_2 FOR FREE SPACE

NRES	K_1	K_2	Φ_{k_i}
5	-0.144931712	0.1020689016	5.426×10^{-10}
10	-0.116192765	0.0734445091	8.979×10^{-14}
15	-0.111802038	0.0692811040	6.444×10^{-16}
20	-0.110322272	0.0678920244	1.963×10^{-17}
25	-0.109646972	0.0672605236	1.264×10^{-18}
30	-0.109282656	0.0669204694	1.208×10^{-19}
35	-0.109063833	0.0667164343	1.283×10^{-20}

Global Phase Error

$$\Phi_{k_i} = \frac{1}{2\pi} \int_0^{2\pi} \left[\frac{k_i - \tilde{k}_i(\theta)}{k_i} \right]^2 d\theta$$

- k_i \equiv physical wave number
- \tilde{k}_i \equiv numerical wave number
- θ \equiv angle of wave through grid



Slide 33

Global Phase Error Vs. Frequency

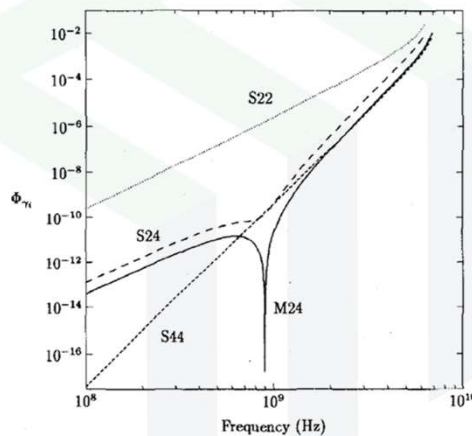


Fig. 3. Frequency bandwidth for the different schemes ($R = 20, f_0 = 900$ MHz). For $f \leq f_0$ the M24 scheme has the least upper bound on the global dispersion error.



Slide 34

Global Phase Error Vs. NRES

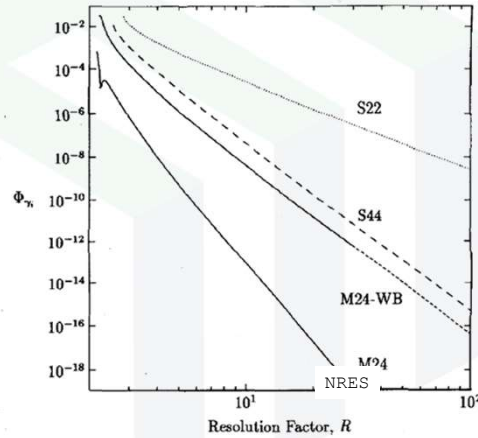


Fig. 4. Global error comparison of the S22, S44, and M24 schemes versus R . The M24-WB is the wideband version of the M24 scheme.

Memory Requirements

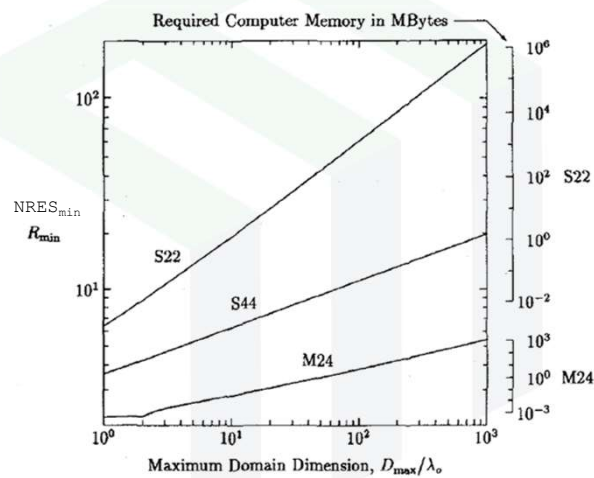


Fig. 5. Minimum resolution factors and computer memory requirements for the S22, S44, and M24 schemes that will keep the total phase error under 5° . Computer memory values are based on 4 bytes per real number and square computational domains that are $D_{max} \times D_{max}$ large.