



Advanced Computation:
Computational Electromagnetics

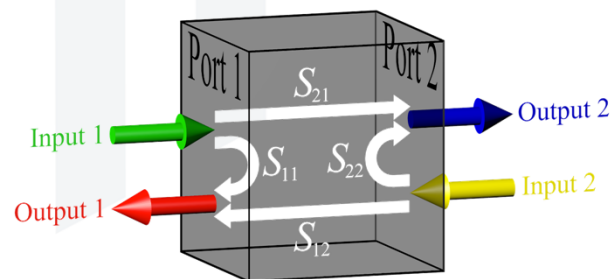
Advanced Networking Concepts



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Outline

- Longitudinally periodic structures
- Dispersion analysis
- Alternatives to scattering matrices



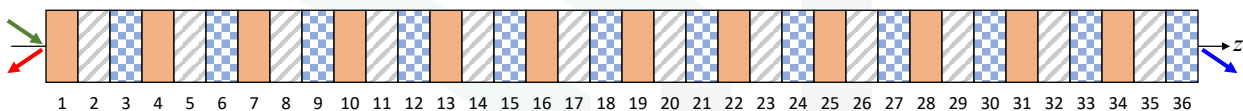
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Longitudinally Periodic Devices

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Longitudinally Periodic Devices (1 of 2)

Suppose it is desired to simulate the following device.



The device has 36 layers. Does this require 36 S -matrix calculations and 35 star products?

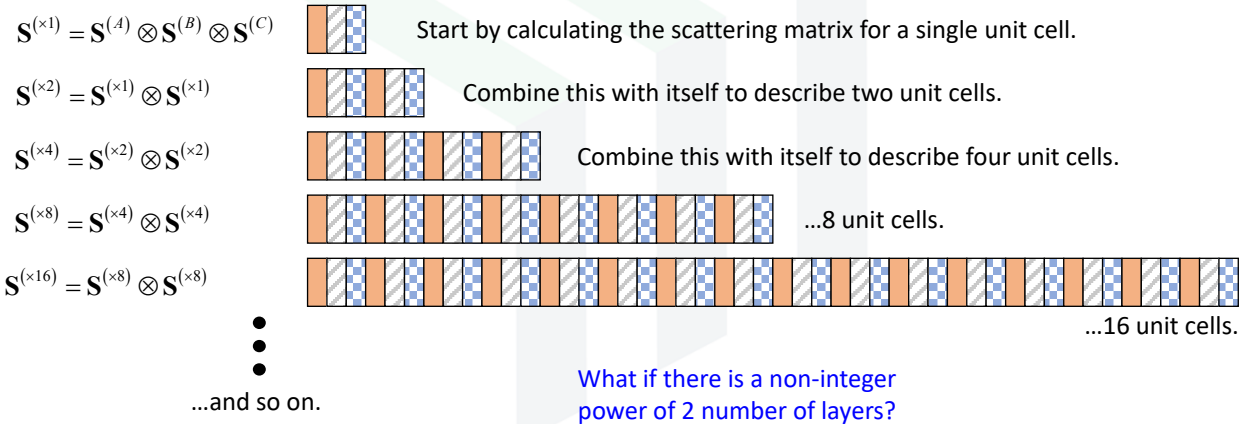
$$\mathbf{S}^{(\times 36)} = \mathbf{S}^{(1)} \otimes \mathbf{S}^{(2)} \otimes \mathbf{S}^{(3)} \otimes \mathbf{S}^{(4)} \otimes \mathbf{S}^{(5)} \otimes \mathbf{S}^{(6)} \otimes \mathbf{S}^{(7)} \otimes \mathbf{S}^{(8)} \otimes \mathbf{S}^{(9)} \otimes \mathbf{S}^{(10)} \otimes \mathbf{S}^{(11)} \otimes \mathbf{S}^{(12)} \otimes \mathbf{S}^{(13)} \otimes \mathbf{S}^{(14)} \otimes \mathbf{S}^{(15)} \otimes \mathbf{S}^{(16)} \otimes \mathbf{S}^{(17)} \otimes \mathbf{S}^{(18)} \\ \otimes \mathbf{S}^{(19)} \otimes \mathbf{S}^{(20)} \otimes \mathbf{S}^{(21)} \otimes \mathbf{S}^{(22)} \otimes \mathbf{S}^{(23)} \otimes \mathbf{S}^{(24)} \otimes \mathbf{S}^{(25)} \otimes \mathbf{S}^{(26)} \otimes \mathbf{S}^{(27)} \otimes \mathbf{S}^{(28)} \otimes \mathbf{S}^{(29)} \otimes \mathbf{S}^{(30)} \otimes \mathbf{S}^{(31)} \otimes \mathbf{S}^{(32)} \otimes \mathbf{S}^{(33)} \otimes \mathbf{S}^{(34)} \otimes \mathbf{S}^{(35)} \otimes \mathbf{S}^{(36)}$$

This is very slow and inefficient!

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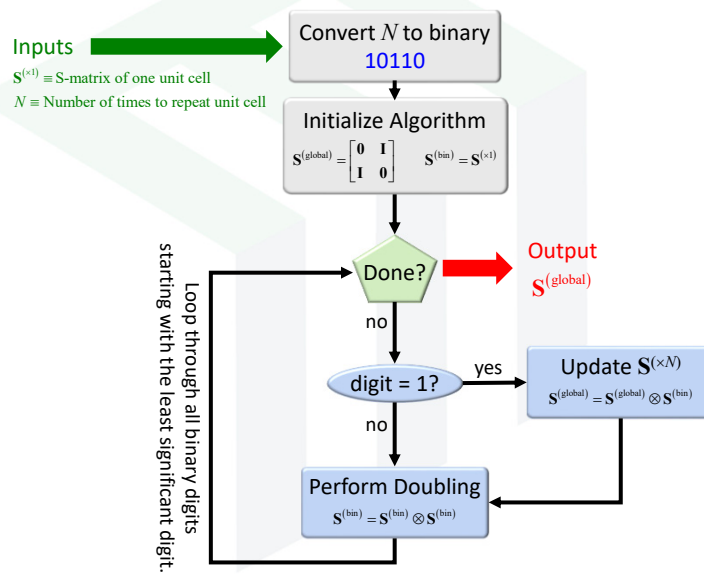
Cascading and Doubling Algorithm

Cascading and double provides a very fast and efficient way to handle devices with many thousands of repeating unit cells.



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Block Diagram for Modified Cascading and Doubling Algorithm



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Example of Cascading and Doubling Algorithm

Step 0 – Calculate scattering matrix for one unit cell

$$S^{(x1)} = S^{(A)} \otimes S^{(B)} \otimes S^{(C)}$$



Inputs to algorithm:

$S^{(x1)}$ ≡ scattering matrix for a single unit cell

$N = 22$ ≡ number of unit cells to combine

Step 1 – Convert N to binary

$$22 \rightarrow \begin{matrix} 16\text{'s} & 8\text{'s} & 4\text{'s} & 2\text{'s} & 1\text{'s} \\ 1 & 0 & 1 & 1 & 0 \end{matrix}$$

Step 2 – Initialize binary and global scattering matrices

$$S^{(bin)} = S^{(x1)} \quad \begin{matrix} S_{11}^{(global)} \equiv 0 \\ S_{12}^{(global)} \equiv I \\ S_{21}^{(global)} \equiv I \\ S_{22}^{(global)} \equiv 0 \end{matrix}$$

Example of Cascading and Doubling Algorithm

Step 3 – Loop through binary digits

$$22 \rightarrow 10110$$

1's digit = 0 → Do not update $S^{(global)}$ $S^{(global)}$ still encompasses 0 unit cells
 → Double $S^{(bin)}$ $S^{(bin)} \equiv S^{(bin)} \otimes S^{(bin)}$ $S^{(bin)}$ now represents 2 unit cells

2's digit = 1 → Update $S^{(global)}$ $S^{(global)} \equiv S^{(global)} \otimes S^{(bin)}$ $S^{(global)}$ now encompasses 2 unit cells
 → Double $S^{(bin)}$ $S^{(bin)} \equiv S^{(bin)} \otimes S^{(bin)}$ $S^{(bin)}$ now represents 4 unit cells

4's digit = 1 → Update $S^{(global)}$ $S^{(global)} \equiv S^{(global)} \otimes S^{(bin)}$ $S^{(global)}$ now encompasses 6 unit cells
 → Double $S^{(bin)}$ $S^{(bin)} \equiv S^{(bin)} \otimes S^{(bin)}$ $S^{(bin)}$ now represents 8 unit cells

8's digit = 0 → Do not update $S^{(global)}$ $S^{(global)}$ still encompasses 6 unit cells
 → Double $S^{(bin)}$ $S^{(bin)} \equiv S^{(bin)} \otimes S^{(bin)}$ $S^{(bin)}$ now represents 16 unit cells

16's digit = 1 → Update $S^{(global)}$ $S^{(global)} \equiv S^{(global)} \otimes S^{(bin)}$ $S^{(global)}$ now encompasses 22 unit cells
 → Double $S^{(bin)}$ $S^{(bin)} \equiv S^{(bin)} \otimes S^{(bin)}$ $S^{(bin)}$ now represents 32 unit cells

Oops! This algorithm performs one unnecessary doubling operation. How can this be fixed?

Dispersion Analysis

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Dispersion Analysis (1 of 2)

An overall scattering matrix is calculated that describes the unit cell.

$$\begin{bmatrix} \mathbf{c}_0^- \\ \mathbf{c}_{N+1}^+ \end{bmatrix} = \begin{bmatrix} \mathbf{S}_{11}^{(\text{uc})} & \mathbf{S}_{12}^{(\text{uc})} \\ \mathbf{S}_{21}^{(\text{uc})} & \mathbf{S}_{22}^{(\text{uc})} \end{bmatrix} \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_{N+1}^- \end{bmatrix} \quad \mathbf{S}^{(\text{uc})} \text{ same as } \mathbf{S}^{(\times 1)} \text{ on previous slide}$$

The terms are rearranged into “almost” the form of a transfer matrix.

$$\begin{bmatrix} \mathbf{0} & -\mathbf{S}_{12}^{(\text{uc})} \\ \mathbf{I} & -\mathbf{S}_{22}^{(\text{uc})} \end{bmatrix} \begin{bmatrix} \mathbf{c}_{N+1}^+ \\ \mathbf{c}_{N+1}^- \end{bmatrix} = \begin{bmatrix} \mathbf{S}_{11}^{(\text{uc})} & -\mathbf{I} \\ \mathbf{S}_{21}^{(\text{uc})} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_0^- \end{bmatrix}$$

If the device is infinitely periodic in the z direction, then the following periodic boundary condition must hold.

$$\begin{bmatrix} \mathbf{c}_{N+1}^+ \\ \mathbf{c}_{N+1}^- \end{bmatrix} = e^{j\beta\Lambda_z} \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_0^- \end{bmatrix} \quad \text{Here } \beta \text{ is the effective propagation constant of the mode.}$$

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Dispersion Analysis (2 of 2)

Substitute the periodic boundary condition into the rearranged equation to get

$$\begin{bmatrix} \mathbf{S}_{11}^{(uc)} & -\mathbf{I} \\ \mathbf{S}_{21}^{(uc)} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_0^- \end{bmatrix} = e^{j\beta\Lambda_z} \begin{bmatrix} \mathbf{0} & -\mathbf{S}_{12}^{(uc)} \\ \mathbf{I} & -\mathbf{S}_{22}^{(uc)} \end{bmatrix} \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_0^- \end{bmatrix}$$

This is a generalized eigen-value problem.

$$\mathbf{Ax} = \lambda \mathbf{Bx}$$

$$\mathbf{A} = \begin{bmatrix} \mathbf{S}_{11}^{(uc)} & -\mathbf{I} \\ \mathbf{S}_{21}^{(uc)} & \mathbf{0} \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} \mathbf{c}_0^+ \\ \mathbf{c}_0^- \end{bmatrix}$$

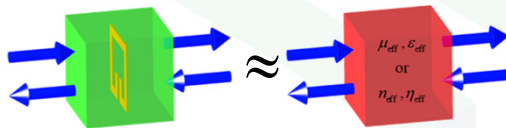
$$\mathbf{B} = \begin{bmatrix} \mathbf{0} & -\mathbf{S}_{12}^{(uc)} \\ \mathbf{I} & -\mathbf{S}_{22}^{(uc)} \end{bmatrix} \quad \lambda = e^{j\beta\Lambda_z}$$

$[\mathbf{V}, \mathbf{D}] = \text{eig}(\mathbf{A}, \mathbf{B}) ;$
 Eigen vectors / Bloch modes Eigen values / β 's

Who Cares?

Given β , it is possible to...

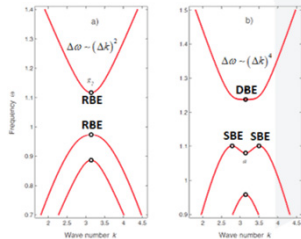
1. Calculate the effective properties of the unit cell.



$$\beta = \omega \sqrt{\mu_{r,eff} \epsilon_{r,eff}}$$

This is an over simplification of parameter retrieval and beyond the scope of this course.

2. Construct band diagrams.

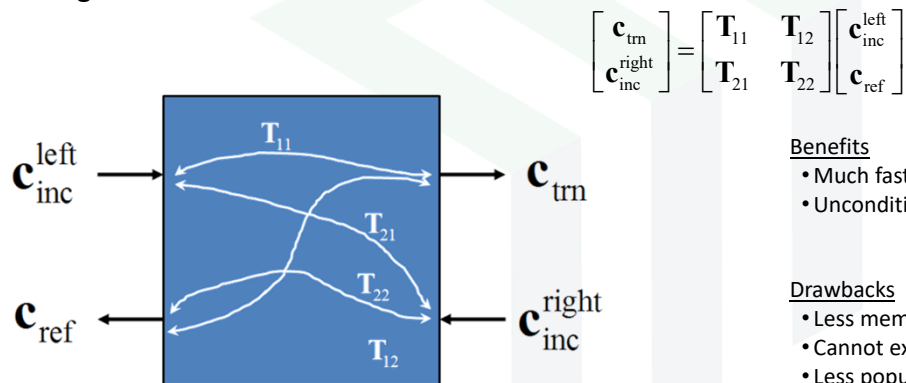


Alternatives to Scattering Matrices

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Transmittance Matrices (T-Matrices)

The T -matrix method is the transfer matrix method where forward and backward waves are distinguished.



Benefits

- Much faster (5 to 10 times)
- Unconditionally stable

Drawbacks

- Less memory efficient
- Cannot exploit longitudinal periodicity
- Less popular in the literature

M. G. Moharam, Drew A. Pommet, Eric B. Grann, "Stable implementation of the rigorous coupled-wave analysis for surface-relief gratings: enhanced transmittance matrix approach," J. Opt. Soc. Am. A, Vol. 12, No. 5, pp. 1077-1086, 1995.

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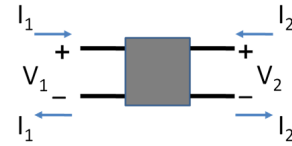
Hybrid Matrices (H-Matrices)

The H -matrix method is borrowed from electrical two-port networks.

$$\begin{bmatrix} V_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \end{bmatrix}$$

$$h_{11} \equiv \left. \frac{V_1}{I_2} \right|_{V_2=0} \quad h_{12} \equiv \left. \frac{V_1}{V_2} \right|_{I_1=0}$$

$$h_{21} \equiv \left. \frac{I_2}{I_1} \right|_{V_2=0} \quad h_{22} \equiv \left. \frac{I_2}{V_2} \right|_{I_1=0}$$



In the framework of fields, the H -matrix is defined as

$$\begin{bmatrix} E_{x,i-1} \\ E_{y,i-1} \\ \tilde{H}_{x,i} \\ \tilde{H}_{y,i} \end{bmatrix} = \begin{bmatrix} \mathbf{H}_{11}^{(i)} & \mathbf{H}_{12}^{(i)} \\ \mathbf{H}_{21}^{(i)} & \mathbf{H}_{22}^{(i)} \end{bmatrix} \begin{bmatrix} \tilde{H}_{x,i-1} \\ \tilde{H}_{y,i-1} \\ E_{x,i} \\ E_{y,i} \end{bmatrix}$$

Claimed Benefits

- Improved numerical stability
- More concise formulation
- Simpler to implement
- Improved numerical efficiency (~30% better than ETM)
- Unconditionally stable

Eng L. Tan, "Hybrid-matrix algorithm for rigorous coupled-wave analysis of multilayered diffraction gratings," J. Mod. Opt., Vol. 53, No. 4, pp. 417-428, 2006.

Reflection Matrices (R-Matrices)

The R -matrix method build on reflection r and transmission t matrices.

$$\begin{bmatrix} \mathbf{u}(z_0) \\ \mathbf{d}(z_{j+1}) \end{bmatrix} = \begin{bmatrix} \mathbf{T}_{uu}^{(j)} & \mathbf{R}_{ud}^{(j)} \\ \mathbf{R}_{du}^{(j)} & \mathbf{T}_{dd}^{(j)} \end{bmatrix} \begin{bmatrix} \mathbf{u}(z_{j+1}) \\ \mathbf{d}(z_0) \end{bmatrix}$$

Claimed Benefits

- Unconditionally stable
- Improved numerical efficiency

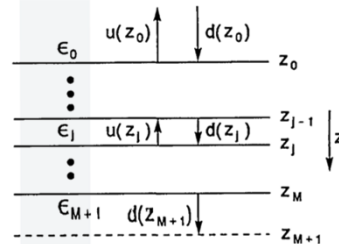


Fig. 1. M -layer stratified grating. The periodic variations of the media in the horizontal direction are not shown.

Lifeng Li, "Bremmer series, R -matrix propagation algorithm, and numerical modeling of diffraction gratings," J. Opt. Soc. Am. A, Vol. 11, No. 11, pp. 2829-2836, 1994.