



Computational Science:
Computational Methods in Engineering

Matrix Operators



Outline

- One-Dimensional Matrix Operators
- Incorporating Boundary Conditions



One-Dimensional Matrix Operators

Slide 3

Functions Vs. Operations (1 of 2)

$$a(x)\frac{\partial^2}{\partial x^2}f(x) + \gamma b(x)\frac{\partial}{\partial x}f(x) + c(x)f(x) = g(x)$$

Operations

Everything else in a differential equation is something that operates on a function.

$a(x), b(x), c(x) \equiv$ point-by-point

multiplication on $f(x)$

$\frac{\partial}{\partial x}, \frac{\partial^2}{\partial x^2} \equiv$ calculates derivatives of $f(x)$

$\gamma \equiv$ scales entire $f(x)$

Functions

Functions only appear in a differential equation as the unknown or as the excitation.

$f(x) \equiv$ unknown

$g(x) \equiv$ excitation

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Functions Vs. Operations (2 of 2)

$$[A][D_x^2][f] + \gamma[B][D_x][f] + [C][f] = [g]$$

Operations

Operations are always stored in square matrices. Any linear operation can be put into matrix form.

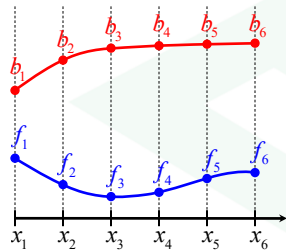
$$[L] = \begin{bmatrix} l_{11} & l_{12} & \dots & l_{1M} \\ l_{21} & l_{22} & \dots & l_{2M} \\ \vdots & \vdots & \ddots & \vdots \\ l_{M1} & l_{M2} & \dots & l_{MM} \end{bmatrix}$$

Functions

Functions are stored as column vectors.

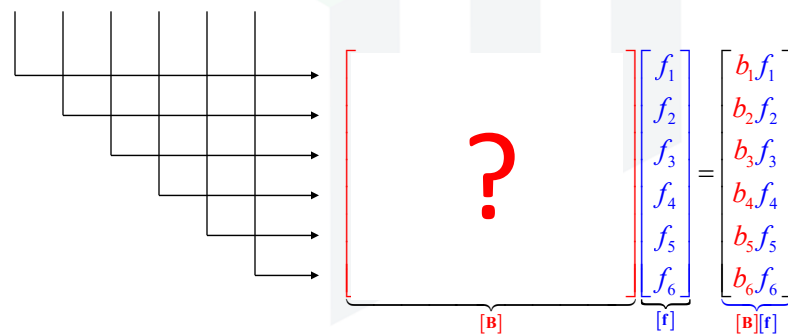
$$[f] = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_M \end{bmatrix} \quad [g] = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_M \end{bmatrix}$$

Point-by-Point Multiplication (1 of 2)

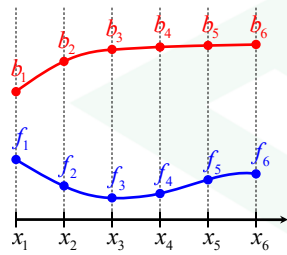


Since the functions are stored in in column-vector form, how are point-by-point multiplications performed using a square matrix?

$$b(x)f(x) \rightarrow [B][f]$$

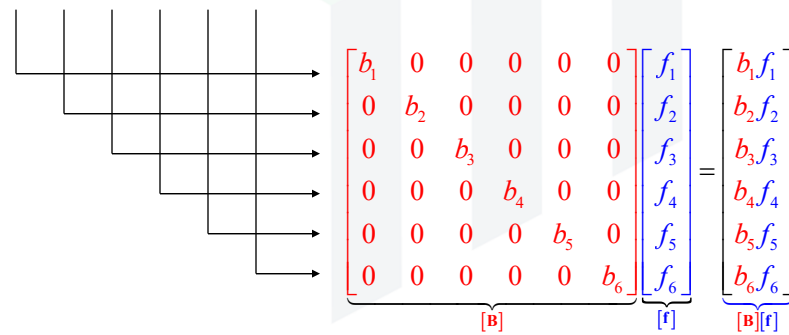


Point-by-Point Multiplication (2 of 2)



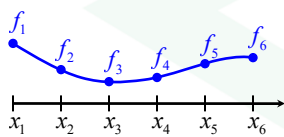
Since the functions are stored in in column-vector form, how are point-by-point multiplications performed using a square matrix?

$$b(x)f(x) \rightarrow [B][f]$$

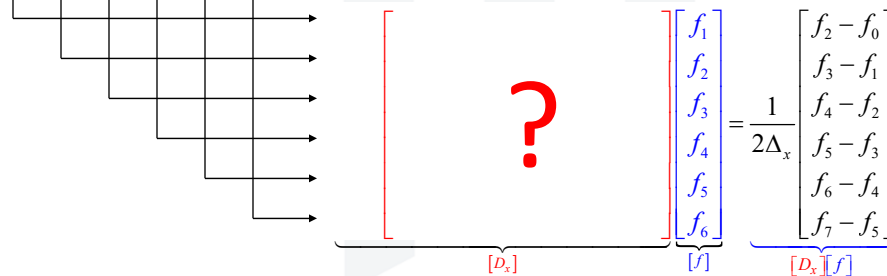


First-Order Partial Derivative (1 of 2)

How can a square matrix be constructed so that when it premultiplies a vector it calculates a vector containing the first-order partial derivative?

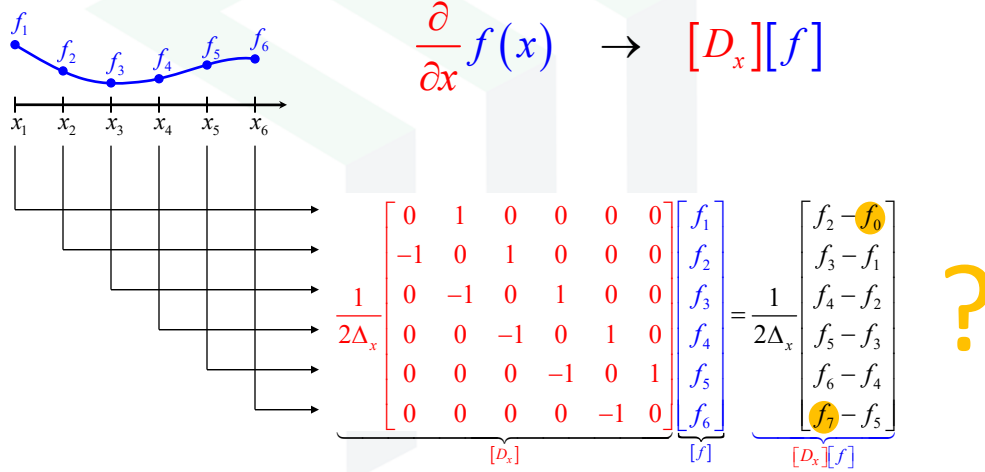


$$\frac{\partial}{\partial x} f(x) \rightarrow [D_x][f]$$



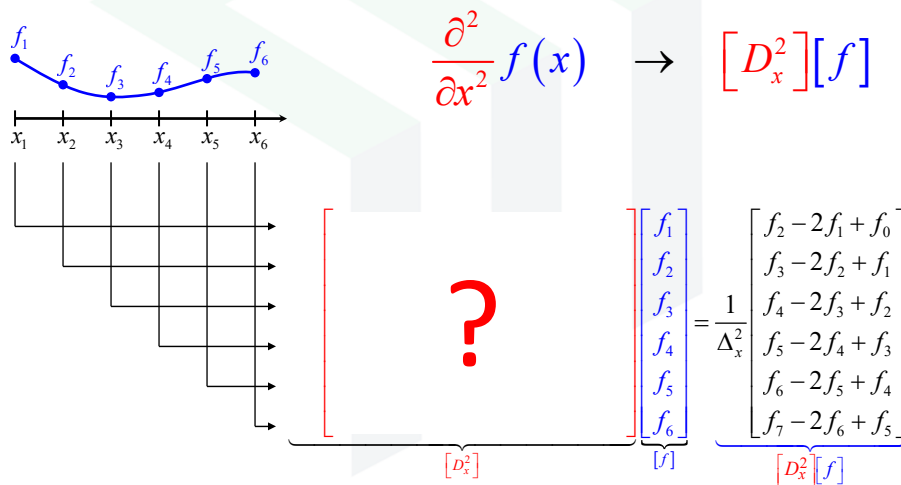
First-Order Partial Derivative (2 of 2)

How can a square matrix be constructed so that when it premultiplies a vector it calculates a vector containing the first-order partial derivative?



Second-Order Partial Derivative (1 of 2)

How can a square matrix be constructed so that when it premultiplies a vector it calculates a vector containing the second-order partial derivative?



Second-Order Partial Derivative (2 of 2)

How can a square matrix be constructed so that when it premultiplies a vector it calculates a vector containing the second-order partial derivative?

$\frac{\partial^2}{\partial x^2} f(x) \rightarrow [D_x^2][f]$

$\frac{1}{\Delta_x^2} \begin{bmatrix} -2 & 1 & 0 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \end{bmatrix} = \frac{1}{\Delta_x^2} \begin{bmatrix} f_2 - 2f_1 + f_0 \\ f_3 - 2f_2 + f_1 \\ f_4 - 2f_3 + f_2 \\ f_5 - 2f_4 + f_3 \\ f_6 - 2f_5 + f_4 \\ f_7 - 2f_6 + f_5 \end{bmatrix}$

Why Are Separate Derivative Matrices Needed for 1st and 2nd-Order Derivative Matrices?

It is known that,

$$\frac{\partial^2}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial}{\partial x}$$

So why can't $\mathbf{D}_x^{(2)}$ simply be calculated as $\mathbf{D}_x^{(2)} = \mathbf{D}_x^{(1)} \mathbf{D}_x^{(1)}$?

It turns out this does not make efficient use of the grid. For a 5-point, 1D grid, this would be

$$\mathbf{D}_x^{(1)} \mathbf{D}_x^{(1)} = \frac{1}{(2\Delta_x)^2} \begin{bmatrix} -1 & 0 & 1 & 0 & 0 \\ 0 & -2 & 0 & 1 & 0 \\ 1 & 0 & -2 & 0 & 1 \\ 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & -1 \end{bmatrix}$$

This is not as accurate because it calculates the derivative with poorer grid resolution than is available.

$$\mathbf{D}_x^{(2)} = \frac{1}{\Delta_x^2} \begin{bmatrix} -2 & 1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 1 & -2 \end{bmatrix}$$

This derivative matrix makes optimal use of the available grid resolution.

USE SPARSE MATRICES!!!!!!!



WARNING !!

The derivative operators will be **EXTREMELY** large matrices.

For a small grid that is just 100×200 points:

Total Number of Points:	20,000
Size of Derivate Operators:	20,000 × 20,000
Total Elements in Matrices:	400,000,000
Memory to Store One Full Matrix:	6 Gb
Memory to Store One Sparse Matrix:	1 Mb

NEVER AT ANY POINT should you use **FULL MATRICES** in the finite-difference method. Not even for intermediate steps. **NEVER!**

Placing Diagonals into Sparse Matrices in MATLAB

```

M = 6;
Z = sparse(M,M);
d = ones(M,1);
A = spdiags(d,0,Z);
    
```

⇒

```

A =
[ 1  0  0  0  0  0 ]
[ 0  1  0  0  0  0 ]
[ 0  0  1  0  0  0 ]
[ 0  0  0  1  0  0 ]
[ 0  0  0  0  1  0 ]
[ 0  0  0  0  0  1 ]
    
```

```

M = 6;
Z = sparse(M,M);
d = ones(M,1);
A = spdiags(-d,-1,Z);
A = spdiags(+d,+1,A);
    
```

⇒

```

A =
[ 0  1  0  0  0  0 ]
[ -1  0  1  0  0  0 ]
[ 0  -1  0  1  0  0 ]
[ 0  0  -1  0  1  0 ]
[ 0  0  0  -1  0  1 ]
[ 0  0  0  0  -1  0 ]
    
```

Incorporating Boundary Conditions

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Dirichlet Boundary Conditions (1 of 2)

The simplest boundary condition is to assume all function values outside of the grid are zero.

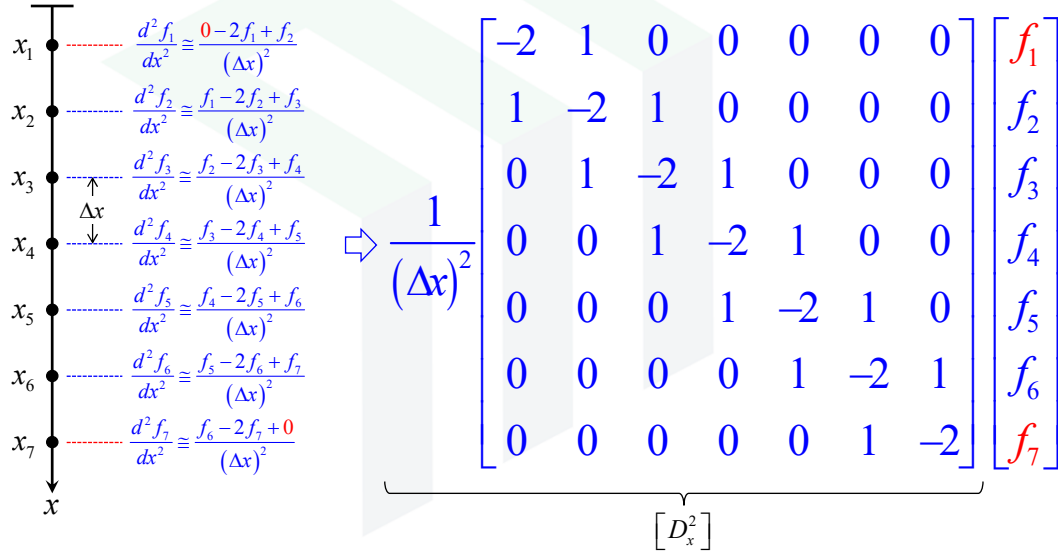
$$\frac{d^2 f_i}{dx^2} \cong \frac{f_{i-1} - 2f_i + f_{i+1}}{(\Delta x)^2}$$

The diagram shows a horizontal axis labeled x with seven discrete points marked as $x_1, x_2, x_3, x_4, x_5, x_6, x_7$. Above each point is a function value $f_1, f_2, f_3, f_4, f_5, f_6, f_7$. A blue bracket spans from x_2 to x_6 , with the general finite difference formula $\frac{d^2 f_i}{dx^2} \cong \frac{f_{i-1} - 2f_i + f_{i+1}}{(\Delta x)^2}$ positioned above it. Below the axis, two red arrows point from x_1 and x_7 to their respective modified formulas:

$$\frac{d^2 f_1}{dx^2} \cong \frac{0 - 2f_1 + f_2}{(\Delta x)^2}$$

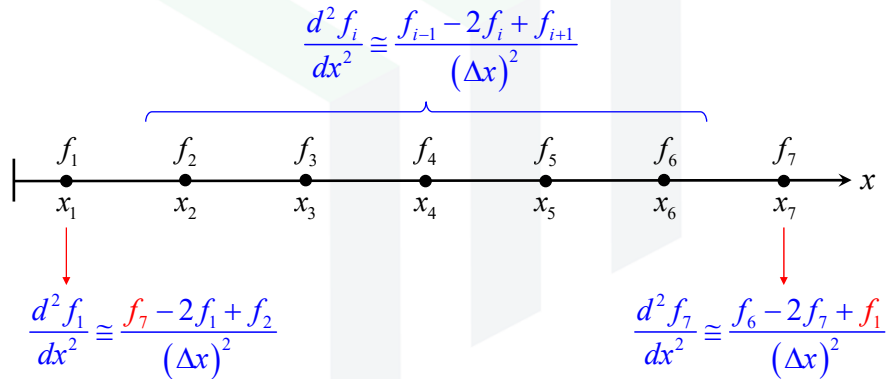
$$\frac{d^2 f_7}{dx^2} \cong \frac{f_6 - 2f_7 + 0}{(\Delta x)^2}$$

Dirichlet Boundary Conditions (2 of 2)



Periodic Boundary Conditions (1 of 2)

If the problem is periodic (i.e. keeps repeating), then the value outside of the grid is the same as the value at the opposite side of the grid.



Periodic Boundary Conditions (2 of 2)

$\frac{d^2 f_1}{dx^2} \cong \frac{f_7 - 2f_1 + f_2}{(\Delta x)^2}$
 $\frac{d^2 f_2}{dx^2} \cong \frac{f_1 - 2f_2 + f_3}{(\Delta x)^2}$
 $\frac{d^2 f_3}{dx^2} \cong \frac{f_2 - 2f_3 + f_4}{(\Delta x)^2}$
 $\frac{d^2 f_4}{dx^2} \cong \frac{f_3 - 2f_4 + f_5}{(\Delta x)^2}$
 $\frac{d^2 f_5}{dx^2} \cong \frac{f_4 - 2f_5 + f_6}{(\Delta x)^2}$
 $\frac{d^2 f_6}{dx^2} \cong \frac{f_5 - 2f_6 + f_7}{(\Delta x)^2}$
 $\frac{d^2 f_7}{dx^2} \cong \frac{f_6 - 2f_7 + f_1}{(\Delta x)^2}$

$$\frac{1}{(\Delta x)^2} \begin{bmatrix} -2 & 1 & 0 & 0 & 0 & 0 & 1 \\ 1 & -2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -2 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \\ f_7 \end{bmatrix} = 0$$

$[D_x^2]$

Neuman Boundary Conditions (1 of 3)

The Neuman boundary condition allows functions to continue linearly off of the grid as if to infinity.

$\frac{df_i}{dx} \cong \frac{f_{i+1} - f_{i-1}}{2\Delta x}$ $\frac{d^2 f_i}{dx^2} \cong \frac{f_{i-1} - 2f_i + f_{i+1}}{(\Delta x)^2}$

$\frac{df_1}{dx} \cong \frac{f_2 - f_1}{\Delta x}$ $\frac{d^2 f_1}{dx^2} \cong 0$ $\frac{df_7}{dx} \cong \frac{f_7 - f_6}{\Delta x}$ $\frac{d^2 f_7}{dx^2} \cong 0$

Neuman Boundary Conditions (2 of 3)

$$\frac{df_1}{dx} \cong \frac{2f_2 - 2f_1}{2\Delta x}$$

$$\frac{df_2}{dx} \cong \frac{f_3 - f_1}{2\Delta x}$$

$$\frac{df_3}{dx} \cong \frac{f_4 - f_2}{2\Delta x}$$

$$\frac{df_4}{dx} \cong \frac{f_5 - f_3}{2\Delta x}$$

$$\frac{df_5}{dx} \cong \frac{f_6 - f_4}{2\Delta x}$$

$$\frac{df_6}{dx} \cong \frac{f_7 - f_5}{2\Delta x}$$

$$\frac{df_7}{dx} \cong \frac{2f_7 - 2f_6}{2\Delta x}$$

$\Rightarrow \frac{1}{2\Delta x}$

-2	2	0	0	0	0	0	0
-1	0	1	0	0	0	0	0
0	-1	0	1	0	0	0	0
0	0	-1	0	1	0	0	0
0	0	0	-1	0	1	0	0
0	0	0	0	-1	0	1	0
0	0	0	0	0	-2	2	0

f_1
f_2
f_3
f_4
f_5
f_6
f_7

$[D_x]$

Neuman Boundary Conditions (3 of 3)

$$\frac{d^2 f_1}{dx^2} \cong 0$$

$$\frac{d^2 f_2}{dx^2} \cong \frac{f_1 - 2f_2 + f_3}{(\Delta x)^2}$$

$$\frac{d^2 f_3}{dx^2} \cong \frac{f_2 - 2f_3 + f_4}{(\Delta x)^2}$$

$$\frac{d^2 f_4}{dx^2} \cong \frac{f_3 - 2f_4 + f_5}{(\Delta x)^2}$$

$$\frac{d^2 f_5}{dx^2} \cong \frac{f_4 - 2f_5 + f_6}{(\Delta x)^2}$$

$$\frac{d^2 f_6}{dx^2} \cong \frac{f_5 - 2f_6 + f_7}{(\Delta x)^2}$$

$$\frac{d^2 f_7}{dx^2} \cong 0$$

$\Rightarrow \frac{1}{(\Delta x)^2}$

0	0	0	0	0	0	0	0
1	-2	1	0	0	0	0	0
0	1	-2	1	0	0	0	0
0	0	1	-2	1	0	0	0
0	0	0	1	-2	1	0	0
0	0	0	0	1	-2	1	0
0	0	0	0	0	0	0	0

f_1
f_2
f_3
f_4
f_5
f_6
f_7

$[D_x^2]$

High-Order Boundary Conditions (1 of 2)

Here we estimate the derivative at the boundaries using special finite-difference equations derived specifically for these points.

$$\frac{d^2 f_i}{dx^2} \cong \frac{f_{i-1} - 2f_i + f_{i+1}}{h^2}$$

$$\frac{d^2 f_1}{dx^2} \cong \frac{2f_1 - 5f_2 + 4f_3 - f_4}{h^2}$$

$$\frac{d^2 f_7}{dx^2} \cong \frac{-f_4 + 4f_5 - 5f_6 + 2f_7}{h^2}$$

High-Order Boundary Conditions (2 of 2)

$$\frac{1}{(\Delta x)^2} \begin{bmatrix} 2 & -5 & 4 & -1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & -1 & 4 & -5 & 2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \\ f_7 \end{bmatrix}$$

$$[D_x^2]$$