



Computational Science:
Computational Methods in Engineering

The Newton-Raphson Method



Outline

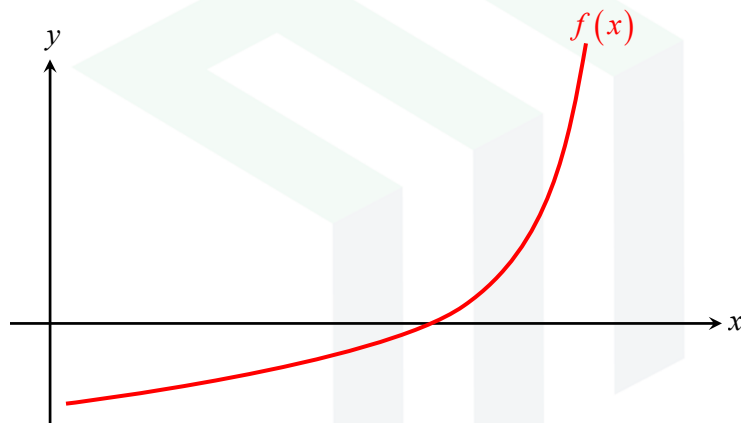
- Description of the Method
- Notes on Implementation
- Example



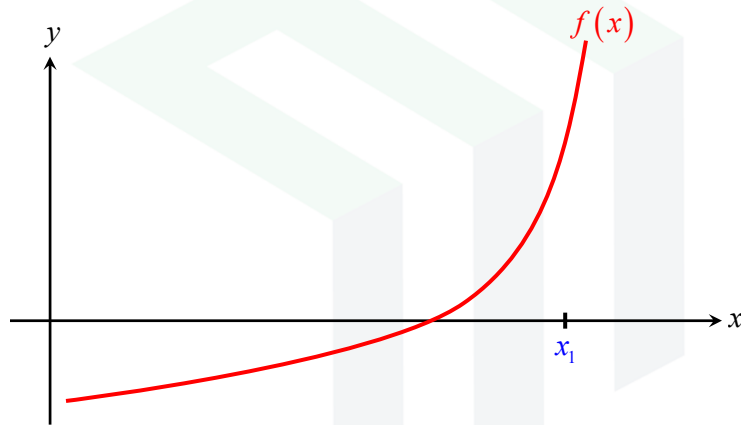
Description of the Method

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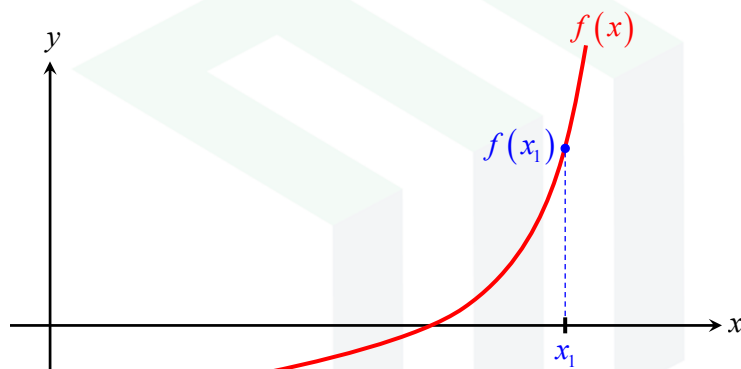
Start with Any Function



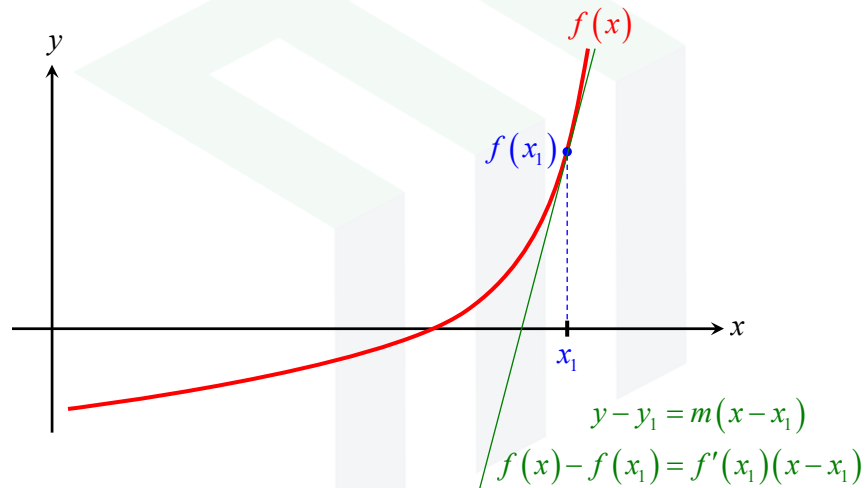
Make an Initial Guess for the Position of the Root x_1



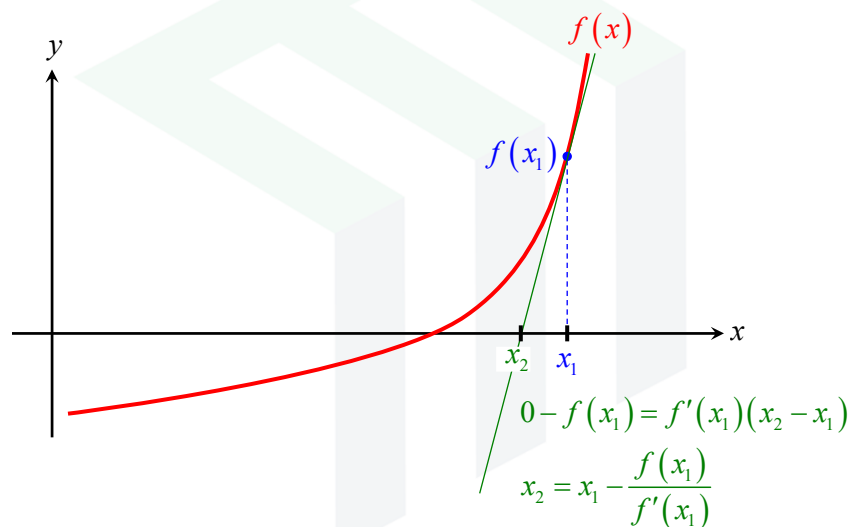
Evaluate the Function at x_1



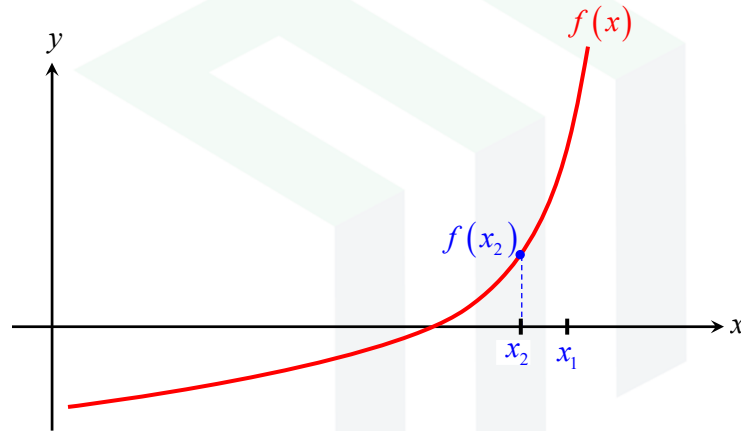
Calculate the Equation of the Line Tangential to the Point on $f(x)$



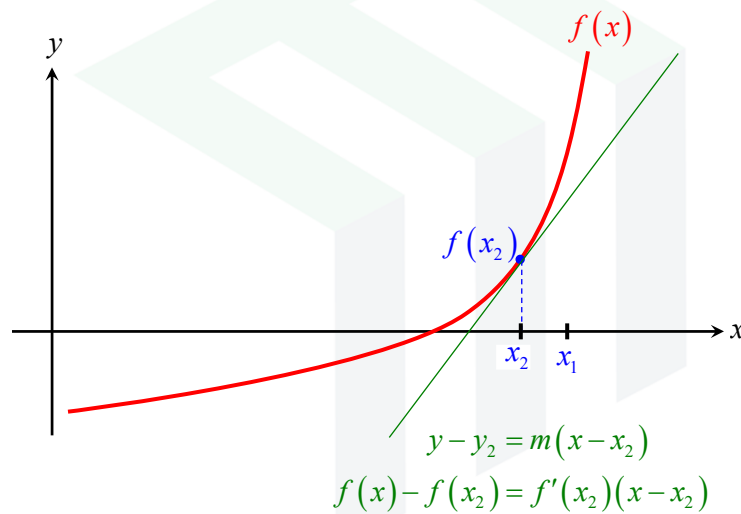
Calculate Where the Line Crosses the x -Axis



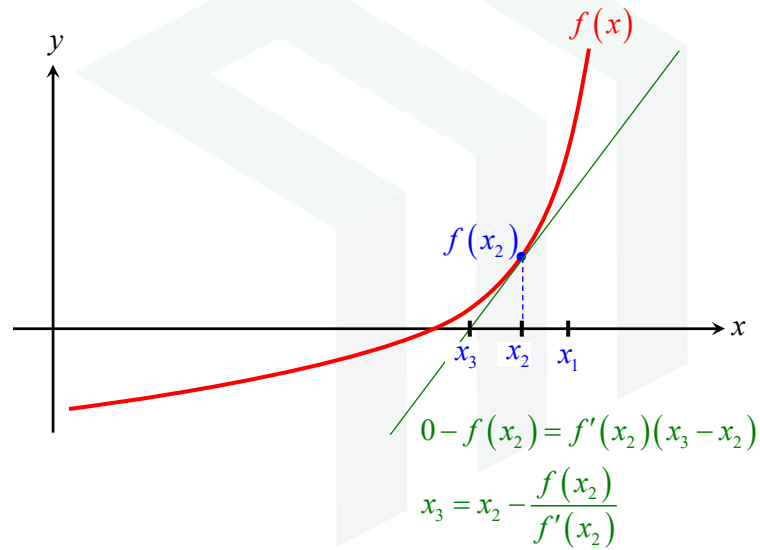
Evaluate the Function at x_2



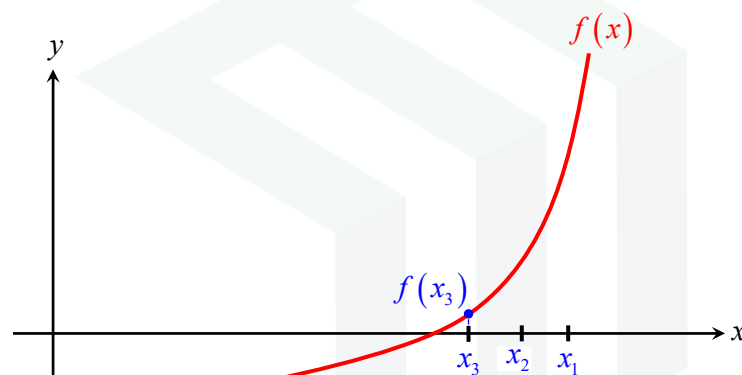
Calculate the Equation of the Line Tangential to the Point on $f(x)$

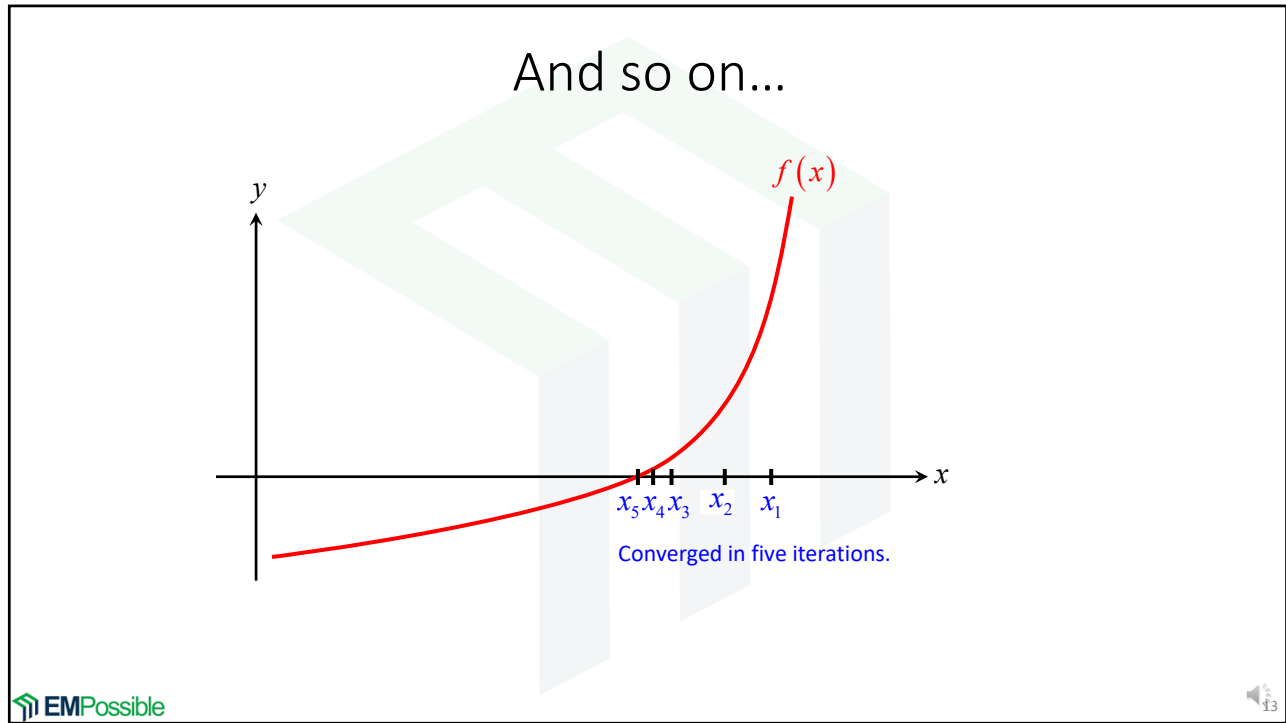


Calculate Where the Line Crosses the x -Axis



Evaluate the Function at x_3

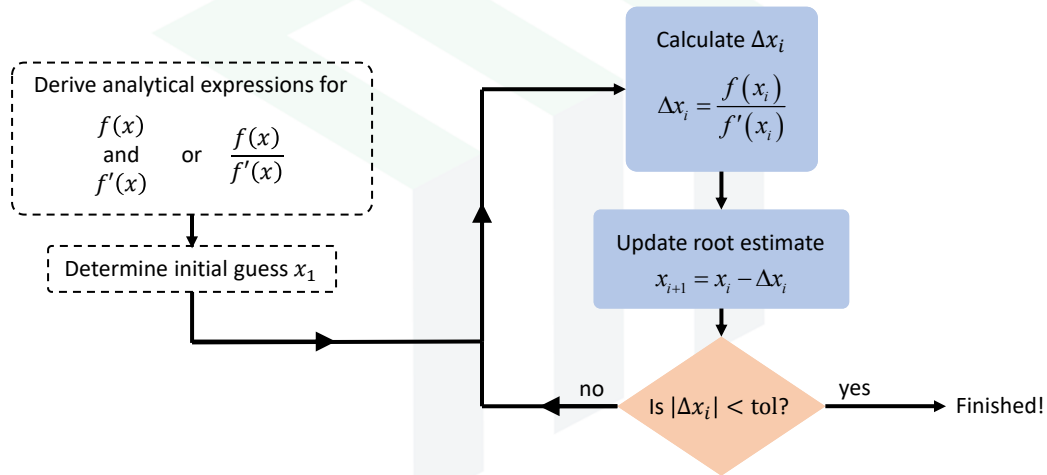




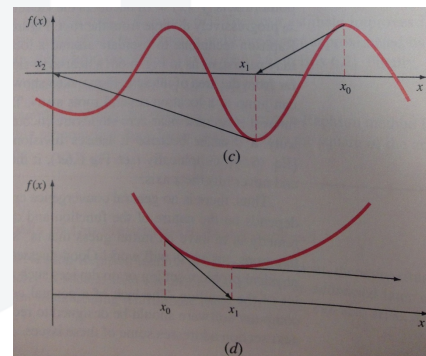
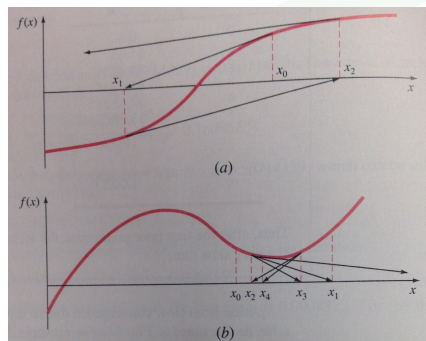
Notes on Implementation

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Block Diagram of Algorithm



Poor or Unstable Convergence



Steven C. Chapra, *Numerical Methods for Engineers*,
7th Ed., McGraw Hill, 2015.

Handling Multiple Roots

If $f(x)$ has multiple roots, perform root finding on the auxiliary function $u(x)$ instead.

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \rightarrow x_{i+1} = x_i - \frac{u(x_i)}{u'(x_i)}$$

The new update equation can be written completely in terms of $f(x)$ and its derivatives as follows.

$$x_{i+1} = x_i - \frac{f(x_i)f'(x_i)}{[f'(x_i)]^2 - f(x_i)f''(x_i)}$$

Notes on Newton-Raphson Method

- Does not require bounds.
- Requires a “good” initial guess.
- Requires $f(x)$ and $f'(x)$ to be analytical.
- Converges extremely fast for functions that are near linear.
- Algorithm vulnerable to instability
- Can converge to the wrong root if multiple roots exist.
- Newton-Raphson Method \neq Newton’s Method
 - While closely related, NRM is for root finding whereas NM is for optimization.

Example

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Example #1

Let $f(x) = \sin x$. What is the root of $f(x)$ in the proximity of $x = 4$?

Step 1 -- Derive analytical expression for $f(x)/f'(x)$

$$\Delta x = \frac{f(x)}{f'(x)} = \frac{\sin x}{\frac{d}{dx} \sin x} = \frac{\sin x}{\cos x} = \tan x$$

This means the update equation is

$$x_{i+1} = x_i - \Delta x_i = x_i - \tan x_i$$

Step 2 -- MATLAB code

```

xr = 4;
tol = 1e-6;
dx = inf;
while abs(dx) > tol
    dx = tan(xr);
    xr = xr - dx;
end

```

Converges to 3.1416 after 4 iterations.

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